## Series 982

## User's Manual

Includes 981, 982, 983 and 984


## 1/8 DIN Microprocessor-Based, Ramping Controller



## Watlow Controls

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## How to Use this Manual

We have designed this user's manual to be a helpful guide to your new Watlow controller. The headlines in the upper right and left corners indicate which tasks are explained on that page. If you are a new user, we suggest that your read through the whole manual. If you are experienced, you may want to begin reading on page 2.1.

## Notes, Cautions and Warnings

We use note, caution and warning symbols throughout this book to draw your attention to important operational and safety information.

A bold text "NOTE" marks a short message in the margin to alert you to an important detail.

A a bold text "CAUTION" safety alert appears with information that is important for protecting your equipment and performance. Be especially careful to read and follow all cautions that apply to your application.

A bold text "WARNING" safety alert appears with information that is important for protecting you, others and equipment from damage. Pay very close attention to all warnings that apply to your application.

The $₫$ symbol (an exclamation point in a triangle) precedes a general CAUTION or WARNING statement.

The 全 symbol (a lightning bolt in a triangle) precedes an electric shock hazard CAUTION or WARNING safety statement.

## Technical Assistance

If you encounter a problem with your Watlow controller, review all of your configuration information for each step of the setup to verify that your selections are consistent with your applications.

If the problem persists after checking all the steps, you can get technical assistance by calling Watlow Controls at (507) 494-5656, between 7 a.m. and 7 p.m. CST, and asking for an applications engineer; or by e-mailing your questions to wintechsupport@watlow.com. When you call, have the following information on hand: the controller's model number (the 12-digit number is printed on the top of the stickers on each side of the controller's case and on the right-hand or top circuit board); your user's manual; all configuration information; and the Diagnostics Menu readings.

## Warranty and Returns

For information about the warranty covering the Series 982 Family of controllers see the Appendix.

## Comments and Suggestions

We welcome your comments and opinions about this user's manual and the Series 982 Family of controllers. Send them to the Technical Editor, Watlow Controls, P.O. Box 5580, Winona, MN 55987-5580. Or call (507) 454-5300 or fax them to (507) 452-4507. The Series 982 User's Manual is copyrighted by Watlow Winona, Inc., © November 1999, with all rights reserved. (1830)

# WATLOW Series 982 User's Manual 

Chapter 1
Starting Out With the Watlow Series 981/982
1.1 Starting Out With the Watlow Series 981/982
1.2 Menu Overview
1.3 DIP Switch Locations and Functions
1.4 Setting the Hardware Lockout DIP Switch
1.5 External Power Supply DIP Switches
1.6 Input Type DIP Switches

## Chapter 2

## Install and Wire the Series 981/982

2.1 Panel Cutout
2.1 Dimensions
2.2 Installation Procedure
2.3 Wiring the Series 981/982
2.4 I/O Isolation
2.4 Power Wiring
2.4 Sensor Installation Guidelines
2.5 Wiring 0-20mA and 4-20mA Process Inputs
2.6 Wiring Example
2.7 Wiring Notes
2.8 Input 1 Wiring
2.9 Input 2 Wiring
2.9 Digital Event Input 2
2.10 Digital Event Input 1
2.11 Output 1 Wiring
2.12 Output 2 Wiring
2.13 Output 3 Wiring
2.14 Output 4 Wiring

## Chapter 3

## Front Panel and Display Loop

3.1 Front Panel Guide
3.2 Display Loop

## Chapter 4

The Setup Menus
4.1 Entering the Setup Menus
4.2 Input Menu
4.3 Input Prompts
4.12 Output Menu
4.13 Output Prompts
4.28 Global Menu
4.29 Global Prompts
4.38 Communications Menu
4.39 Communications Prompts

## Chapter 5

## The Operation Menus

5.1 Entering the Operation Menus
5.2 System Menu
5.3 System Prompts
5.10 PID Menu
5.11 PID Prompts

## Chapter 6

The Factory Menus
6.1 Entering the Factory Menus
6.2 Diagnostics Menu and Prompts
6.7 Calibration Menu and Prompts

Chapter 7
The Run Menu
7.1 Program Menu
7.1 Program Prompts
7.5 Running a Series 982 Profile
7.5 Resume a Profile
7.6 Run and Pre-Run Menus
7.6 Event Outputs
7.7 Guaranteed Soak Deviation
7.8 Jump-loops
7.8 Programming a Ramping Profile
7.10 Running your Profile
7.10 Editing your Profile
7.12 Linking Profiles
7.13 Waitfor Functions
7.14 Master Step Chart

## Chapter 8

Operation, Tuning, Alarms and Error Codes
8.1 Auto-tuning
8.2 Manual Tuning
8.3 Changing the Output 3 Jumper
8.4 Using Alarms
8.5 Error Code E1 and E2 Messages
8.6 Error Code Actions

Chapter 9
Software
9.2 Burst Fire
9.4 Communications
9.6 Dead Band
9.8 Digital Events
9.10 Input Filter
9.12 Input Linearization
9.14 Retransmit
9.16 Slidewire Feedback

## Appendix

A. 1 Warranty and Returns
A. 2 Glossary
A. 5 Index
A. 8 Specifications
A. 9 Ordering Information
A. 10 Declaration of Conformity

Notes

## Chapter 1 Starting Out with the Watlow Series 982

Figure 1.1 Watlow Ramping Controllers.


Watlow's Series 982, a $1 / 8$ DIN microprocessor-based ramping controller, is truly an innovation in the controller field. The Series 982 provides 6 -step program capability, with up to 4 files possible.

The new controller meets a wide variety of needs in the process industries. Its broad range of I/O options allows control of virtually any process variable. In addition to the standard Watlow features, the Series 982 has expanded auto-tuning capabilities and increased alarm functionality.

If you are unfamiliar with general controller operation, it's a good idea to read through the entire manual. The manual is organized in chronological order with each chapter broken down by wiring, menus, operation and applications. If you understand the concept of process/temperature controllers and feel comfortable skipping around through the manual, use the index or the black tabs at the top of each page to quickly scan the pages and find the topic you are looking for.

The map on the next page provides an overview of all menus and prompts and how to navigate between them. There are three main prompts Setup, Operation and Factory (SEE, BPEr and FcEB). Beneath these prompts there are several menus. The Display Loop can be reached from anywhere using the Display key.

Display Loop
(Lower Display)

Press sumw to exit any menu and reach the Display Loop at any time.


| Operation Menus |  | Operation $\quad \mathrm{OPEr}(\mathrm{C}$ |  |
| :---: | :---: | :---: | :---: |
|  |  |  |
| From the Display |  |  |  |
| Loop, press mode to | $\rightarrow$ (SyS) (System) |  | (Pid) (PID) | (Prog) (Program) |
| advance to the OPEr prompt. | Ei1S ( ) Event input 1 status | Pb1 () Output 1 proportional band | FiLE () File number |
|  | Ei2S ( ) Event input 2 status | re1 ( ) Output 1 reset | 4 StEP ( ) Step number |
|  | Ent3 () Event output 3 status | It1 () Output 1 integral | 4 StyP () Step type |
|  | Ent4 () Event output 4 status | rA1 () Output 1 rate |  |
|  | 4 A2LO ( ) Alarm 2 low | dE1 ( ) Output 1 derivative | * |
|  | A2HI ( ) Alarm 2 high | Ct1 () Output 1 cycle time |  |
|  | A3LO ( ) Alarm 3 low | Pb2 () Output 2 proportional band |  |
|  | A3HI ()Alarm 3 high | rE2 ( ) Output 2 reset |  |
|  | A4LO ()Alarm 4 low | It2 () Output 2 integral | (See Chapter 7 |
|  | A4HI ( ) Alarm 4 high | rA2 ( ) Output 2 rate | for all the |
|  | ( AUt () Auto-tune | dE2 () Output 2 derivative | Program menus.) |
|  |  | Ct2 ( ) Output 2 cycle time |  |
|  |  | db () Dead band |  |

## Setup Menus

From the Display Loop, press and $\int$ for 3 seconds to enter the Setup menus.
move between the menus.

Press mode to advance through a menu.

Hold mode while pressing $\triangle$ to move backwards through the menus.

Press $\boldsymbol{\square}$ or to select prompt values.

Figure 1.2 The Series 982 Map.


## DIP Switch Locations and Functions

The Series 982 has several Dual In-line Package (DIP) Switches inside the control. Depending on your model number, your unit can have as few as one DIP switch or as many as five DIP switches. Use the rest of this chapter as a DIP switch reference guide.

To set any DIP switch:

1. Remove the control chassis from the case. Release the two tabs on one side of the bezel, by pressing in firmly on each until you hear the tab snap. Release the two tabs on the opposite side of the control. You may need to rock the bezel back and forth several times to release the chassis.
2. Use the following graphics in the rest of the chapter to locate and identify each DIP switch and the desired settings.

Figure 1.3 -
Press the release tabs to remove the controller chassis.



CAUTION:
There is danger of an explosion if the battery is incorrectly replaced. This battery is factory replaceable only. Dispose of used batteries according to manufacturer's recommendations.

Figure 1.4 -
Battery backup and hardware lockout DIP switches.

## The Hardware Lockout/Battery Backup DIP Switch

All units are equipped with a DIP switch for hardware lockout of the SEt and Fcty prompt menus, and to enable battery backup of the Run parameters. The location of the board and switch appear below. The switches are clearly numbered, and are labeled on the outside of the board. When Switch \#1 is on, battery backup is enabled. When Switch \#2 is on, the menus under the SEt prompt (Input, Output, Global and Communications) and Fcty prompt (Diagnostics and Calibration) cannot be viewed. When the control leaves the factory switch \#1 is on and switch \#2 is off.


Control Chassis Top View (982 \& 984) Left-side View (981 \& 983)
battery backup of Run prompts
lockout Setup and Factory menus


| Input | Output | Global | Communications |
| :---: | :---: | :---: | :---: |
| NFE | CLFE | SxH2 | EPV7 |
| CET | CET | CEt | CET |

Diagnostics Calibration


## External Power Supply DIP Switches (Option "T")

Table 1.5-
Power Supply DIP Switch Settings.

Models equipped with an external signal conditioner power supply (Option "T"), have a DIP switch for selecting the power supply voltage. Output 2, 3 or 4 can be ordered with the external power supply. The location of each board and DIP switch appear below. When the control leaves the factory, both switches are off. The figures below show a PC board cutaway for each DIP switch. See the table to the left

| Voltage/Load Current | S 1 | S2 |
| :---: | :---: | :---: |
| $5 \mathrm{~V} \pm 5 \% @ 30 \mathrm{~mA}$ | On | On |
| $12 \mathrm{~V} \pm 5 \% @ 30 \mathrm{~mA}$ | On | Off |
| $20 \mathrm{~V} \pm 5 \% @ 30 \mathrm{~mA}$ | Off | Off | for the power supply switch settings. The settings can be used for all three output DIP switches. For other voltage or current ratings contact the factory.

Figure 1.5aOutput 2 External Signal Conditioner Power Supply.

Figure 1.5b-
Output 3
External Signal
Conditioner
Power Supply.


## Universal Signal Input Type DIP Switches

Remove the chassis from the case. Looking at the back of the control, the input \#1 (In1) switch is located at the base of the unit. Set the DIP switches to match the appropriate sensor input types will automatically match the DIP switch settings.

If you have model number 98_C- $\underline{\mathbf{1}}$ _ _ _-_ _ _ , there is no In1 DIP switch.


Figure 1.6aInput DIP Switch Locations.

## Single Input Unit

98_C-2_-- - - - -


J, K, T, N, C, E, Pt2, D Thermocouple Input


RTD Input


R, S, B Thermocouple Input


0-20mA or 4-20mA Input

Figure 1.6bInput DIP Switch Settings.

$0-5 \mathrm{~V}, 1-5 \mathrm{~V}$ or $0-10 \mathrm{~V}$ Input

## Chapter 2 Installation and Wiring

NOTE:
Space panel cutouts at least 1.66 inches (42.2mm) apart.

## NOTE:

Adjustable mounting brackets can be side-mounted.

NOTE:
Holes can be cut in the panel using a Greenlee 1/8 DIN Hydraulic Kit \#60068 (punch \#60069, die \#60070).

Figure 2.1 -
Series 981 and
Series 982 dimensions.


## Installing the Series 982

Installing and mounting requires access to the back of the panel.

1. Make a panel cutout.
2. To remove the controller chassis from its case, press in firmly on the two tabs on one side or the top of the bezel until they unsnap, then unsnap the two tabs on the opposite side or the bottom. Pull the chassis out of the case by gently rocking it.
3. Slide the case into the panel cutout. Check to see that the gasket is not twisted, and is seated within the case bezel flush with the panel. Slide the mounting collar over the back of the control.

Figure 2.2 Side and top view.


## Installation



CAUTION: Follow the installation procedure exactly to guarantee a proper NEMA 4X seal. Make sure the gasket between the panel and the rim of the case is not twisted and is seated properly. Failure to do so could result in damage to equipment.
4. Loosen the mounting bracket screws enough to allow for the mounting collar and panel thickness. Place each mounting bracket into the mounting slots (head of the screw facing the back of the controller). Push each bracket backward then down to secure it to the control case. To guarantee a proper NEMA 4X seal, Series 982 and 984 units (vertical) must have the mounting brackets located on either side of the unit. When installing Series 981 and 983 units (horizontal) the brackets must be on the top and bottom of the unit.
5. Make sure the case is seated properly. Tighten the installation screws firmly against the mounting collar to secure the unit. To ensure a NEMA 4X seal, there should be no space between the bezel and panel. Overtightening the screws will distort the case and make it difficult to remove or replace the controller.
6. Insert the controller chassis into its case and press the bezel until all four tabs snap. Make sure the inside gasket is seated properly and not twisted.
7. To release the mounting brackets, loosen the mounting bracket screws and push the brackets forward, then pull it up and out.


WARNING: To avoid potential electric shock, use National Electric Code (NEC) safety practices when wiring and connecting this unit to a power source and to electrical sensors or peripheral devices. Failure to do so could result in injury or death.

## NOTE:

Input-to-output isolation is defeated when the external signal conditioner power supply option is used to power a transmitter connected to input 1.

Figure 2.4 -
Power wiring.


CAUTION: If high voltage is applied to the low voltage unit, irreversible damage will occur.

## Wiring the Series 982

Wiring options depend on the model number and DIP switch settings. Check the terminal designation stickers on either side of the controller and compare your model number to those shown here and with the model number breakdown on the inside back cover of this manual.

## Input-to-output Isolation

The Series 982 uses optical isolation between the analog inputs and the controller outputs/digital input. This isolation provides a 500V~ (VAC) barrier to prevent ground loops when using grounded sensors and/or peripheral equipment.

Here is a breakdown of the isolation barriers:

- Analog inputs 1 and 2 are grouped together.
- Outputs 1 through 4 and the standard event input are grouped together.

This does not apply to Output 4 when configured as communications.

- The digital communications output (4) is separate from the above groups.


## Power Wiring

100 to $\mathbf{2 4 0} \mathrm{V} \sim(\mathrm{ac})$, nominal ( 85 to 264 actual)

| Horizontal Package | 981 C - |
| :---: | :---: |
| Vertical Package | $982 \mathrm{C}-\ldots-{ }^{-}$- |

24 to $28 \mathrm{~V}=(\mathrm{ac} / \mathrm{dc})$, nominal (21 to 30 actual)

```
Horizontal Package
Vertical Package
98 3 C -
984 C -
```

$\qquad$


## Sensor Installation Guidelines

Thermocouple input: Extension wire for thermocouples must be of the same alloy as the thermocouple itself to limit errors.
$100 \Omega$ RTD input: Each $1 \Omega$ of lead wire resistance can cause a $+2^{\circ} \mathrm{F}$ error when using a two-wire RTD. A three-wire RTD sensor overcomes this problem. All three wires must have the same electrical resistance (i.e., same gauge, same length, multi-stranded or solid, same metal).

Maintain isolation between input 1 and input 2 to prevent a ground loop. A ground loop may cause incorrect readings, dashes across the upper display or the display of error codes.

## Wiring 0-20 and 4-20mA Process Inputs

Figure 2.5 -
Process wiring example.

Certain "transmitters" used in process input applications are producing internal resistor failures in the Watlow Series 988 family of controllers. This is only apparent with the Series 988 family $1 / 8$ DIN units with Process Inputs selected (0-20mA or 4-20mA dc only).

We are noticing that an external resistor is required to prevent a high in-rush current which burns out the Series 988 family controllers' 7-ohm internal resistor. This high in-rush current occurs initially on "power-up." If the transmitter turns full on for a split second during power-up, the available current weakens or damages the internal resistor.
Example: $20 \mathrm{~V} / 7$ ohms $=2,857 \mathrm{~mA}$ (too much!).
The wiring diagram example below shows an application where a customer is using a $4-20 \mathrm{~mA}$ dc transmitter and power supply to feed the input of a Series 988 controller. The Rx range ( 100 to 400 ohms) for the external resistor is recommended. We suggest starting with 250 ohms.

Example: Customer is using a $24 \mathrm{~V}=$ (dc) power supply to power up the 4-20mA dc transmitter that inputs to the Series 988 terminals 8 (-) and 10 (+). To figure out what the internal Series 988's handling current is for the $0-20 \mathrm{~mA}$ or $4-20 \mathrm{~mA}$ dc input to the Series 988 controllers, we need to apply Ohm's Law: The square root of Watts divided by Resistance equals Current. Applying that formula to the example below produces the following: Square Root of ( 0.125 Watts $/ 7$ ohms) $=134 \mathrm{~mA}$ dc (handling input current). This is the acceptable input current for the Series 988 universal input board.


Reminder, the input impedance of 7 ohms handles the majority of our customer applications; the external resistor ( Rx ) is only for certain transducers/transmitters that spike on power-up or power-down. Please make sure your customer's transmitter / transducer fall within our Series 988 family ( $1 / 8 \mathrm{DIN}$ ) of controllers' Process Input specification of 7 ohms input impedance.

## Wiring Example



## WARNING:

To avoid potential electric shock, use National Electric Code (NEC) safety practices when wiring and connecting this unit to a power source and to electrical sensors or peripheral devices. Failure to do so could result in injury or death.


WARNING: Install high or low temperature limit control protection in systems where an over temperature fault condition could present a fire hazard or other hazard. Failure to install temperature limit control protection where a potential hazard exists could result in damage to equipment, property and injury to personnel.


WARNING:
To avoid damage to property and equipment, and/or injury of loss of life, use National Electric Code (NEC) standard wiring practices to install and operate the Series 982. Failure to do so could result in such damage, and/or injury or death.

Figure 2.6 -
System wiring example.



WARNING:
To avoid damage to property and equipment, and/or injury of loss of life, use National Electric Code (NEC) standard wiring practices to install and operate the Series 982. Failure to do so could result in such damage, and/or injury or death.


NOTE:
Sketch in your application on this page or a copy of it. See wiring examples in this chapter.

Figure 2.7 -
Wiring notes.

## NOTE:

Successful installation requires five steps:

- Model number and software choice
(Appendix);
- DIP switch settings (Chapter 1);
- Sensor match
(Chapter 2 and
Appendix);
- Sensor installation
(Chapter 2); and
- Wiring (Chapter 2).


CAUTION:
An external resistor is required for $0-20 \mathrm{~mA}$ and $4-20 \mathrm{~mA}$ process wiring to prevent a high inrush current which could burn out the controller's 7 -ohm resistor. See page 2.5 for recommendations.

Figure 2.8a - Thermocouple
Thermocouple only
98 _ C - $\underline{1}_{\text {_ _ _ _ _ _ _ (no DIP switches) }}$
Universal signal conditioner
98 $\qquad$ C-2 $\qquad$ -

Input impedance: $20 \mathrm{M} \Omega$


Figure 2.8b - RTD (2- or 3-wire)
Universal signal conditioner


Figure $2.8 \mathrm{c}-0-5 \mathrm{~V}=1-5 \mathrm{~V}=$ or $0-10 \mathrm{~V}=$ (dc) Process
Universal signal conditioner

$$
98 \_ \text {C }-\underline{2}--_{-}^{-}---
$$

Input impedance: $10 \mathrm{~K} \Omega$


Figure $2.8 \mathrm{~d} \mathbf{- 0 - 2 0 m A}$ or $\mathbf{4 - 2 0 m A}$ Process
Universal signal conditioner 98 _ C - 2 $\qquad$ _ _ - -

Input impedance: $7 \Omega$


NOTE:
See Chapter 9 for information on slidewire feedback.

## NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match
(Chapter 2 and
Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

Figure 2.9a - Slidewire Feedback or Potentiometer Input
98 _ C - _ ${ }^{3}$ _ - _ _ _
Slidewire resistance: 100 to $1,200 \Omega$


Figure 2.9b - Digital Event Input 2
98 _ $\mathrm{C}_{-} \mathbf{5}_{\text {_ }}{ }^{-}$_ ${ }^{-}$
$0-3 V=$ (dc) Event Input 2 off (open)
14-36V $=$ (dc) Event Input 2 on (closed)



## Event Input 1 Wiring

Figure 2.10 - Digital Event Input 1

## NOTE:

Successful installation requires five steps:

- Model number and software choice
(Appendix);
- DIP switch set-
tings (Chapter 1);
- Sensor match
(Chapter 2 and
Appendix);
- Sensor installation
(Chapter 2); and
- Wiring (Chapter 2).

Available on all units.
14-36V=(dc) Event Input 1 off (open) $0-3 V=$ (dc) Event Input 1 on (closed)


Figure 2.11a - AC Outputs

## NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix); - DIP switch settings (Chapter 1); - Sensor match (Chapter 2 and Appendix);
- Sensor installation
(Chapter 2); and
- Wiring (Chapter 2).

Solid-state Relay with Contact Suppression
98 _ C - _ B _ $^{-}$_ _ _
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$

Electromechanical Relay with Contact Suppression (NO and COM contacts only)
98 _ C

- _ _ D -
- _ - _ -

Form C, 5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$
Electromechanical Relay without Contact Suppression
98 _ C - _ E _ - _ _ _
Form C, 5 amps off-state impedance: $31 \mathrm{M} \Omega$


Solid-state Relay without Contact Suppression
98 _ $\mathrm{C}_{-}$_ $\underline{\mathrm{K}}$ _
_ _ _ -
0.5 amps , off-state impedance: $31 \mathrm{M} \Omega$

Figure 2.11b - Switched DC, Open Collector
98 _ C - _ _ C _ - _ _ -
Minimum load resistance: $500 \Omega$


Figure $2.11 \mathrm{c}-\mathbf{0 - 2 0 m A}$ and $4-20 \mathrm{~mA}$ Process


Maximum load impedance: $800 \Omega$


Figure 2.11d $-0-5 \mathrm{~V}=, 1-5 \mathrm{~V}=$ and $0-10 \mathrm{~V}=$ (DC) Process 98 _ C - _ $\mathbf{F}_{\text {_ }}$

Minimum load impedance: $1 \mathrm{~K} \Omega$


## Figure 2.12a - AC Outputs

Solid-state Relay with Contact Suppression
98 $\qquad$ C - $\qquad$ B $\qquad$
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$

Electromechanical Relay with Contact Suppression (NO and COM contacts only)
98 _ C $\qquad$ D


Form C, 5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$
Electromechanical Relay without Contact Suppression 98 _ C $\qquad$ E $\qquad$


Form C, 5 amps off-state impedance: $31 \mathrm{M} \Omega$
Solid-state Relay without Contact Suppression
98 C $\qquad$ K $\qquad$
0.5 amps , off-state impedance: $31 \mathrm{M} \Omega$

Figure 2.12b - Switched DC, Open Collector
NOTE:
This output cannot be configured as an event ouput.

NOTE:
If $[\mathrm{LL}, \mathrm{d}]$ is selected
for ine, DEC prompt will not appear.

NOTE:
Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1.

98 _
C - $\qquad$ C $\qquad$
Minimum load resistance: $500 \Omega$


Figure $2.12 \mathrm{c} \mathbf{- 0 - 2 0 m A}$ and 4-20mA Process
98 _ C _ _ _ F - _ _ _
Maximum load impedance: $800 \Omega$


Figure 2.12d $-0-5 \mathrm{~V}=$, $1-5 \mathrm{~V}=$ and $0-10 \mathrm{~V}=$ (DC) Process
$\qquad$
Minimum load impedance: $1 \mathrm{~K} \Omega$


Figure 2.12e - External Signal Conditioner Power Supply 98 _ $\mathrm{C}^{-}$_ _ _ $\mathrm{T}^{-}$_ _ _ _
NOTE:
See Chapter 1 for DIP switch location and settings.


## NOTE:

Successful installation requires five steps:

- Model number and software choice (Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

Figure 2.13a - AC Outputs
Solid-state Relay with Contact Suppression
98 _ C $\qquad$ - B _ _ _
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$

Electromechanical Relay without Contact Suppression
98 C - _-_ - J _ _ - -
Form A or B, 5 amps , off-state impedance: $31 \mathrm{M} \Omega$
Solid-state Relay without Contact Suppression
98 _ C $\qquad$ - K
_ - - -
0.5 amps , off-state impedance: $31 \mathrm{M} \Omega$


Figure 2.13b - Switched DC
98 _ C - $\qquad$ - $\underline{C}$ _ - -

Minimum load resistance: $500 \Omega$


Figure 2.13c - Process Retransmit
0-20mA, $4-20 \mathrm{~mA}$, Load impedance: $600 \Omega$ max.
98 _ C $\qquad$ - 쓴 $\qquad$
$0-5 \mathrm{~V}=$, $1-5 \mathrm{~V}=$, $0-10 \mathrm{~V}=$ (dc), Load impedance: $500 \Omega \mathrm{~min}$.
98 _ C $\qquad$

Figure 2.13d - External Signal Conditioner Power Supply
98 _ C - _ _ _ _ - $\mathbf{T}^{\text {_ _ _ }}$

## NOTE:

See Chapter 1 for DIP switch location and settings.

NOTE:
Input-to-output isolation is defeated when the external signal conditioner power supply is used to power a transmitter connected to input 1.


NOTE:
Successful installation requires five steps:

- Model number and software choice
(Appendix);
- DIP switch settings (Chapter 1);
- Sensor match (Chapter 2 and Appendix);
- Sensor installation (Chapter 2); and
- Wiring (Chapter 2).

NOTE:
Input-to-output isolation is defeated when the external transmitter power supply is used to power a signal conditioner connected to input 1.

Figure 2.14a - AC Outputs

Solid-state Relay with Contact Suppression
98 _ C $\qquad$ - _ B -
0.5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$

Electromechanical Relay with Contact Suppression
(NO and COM contacts only)
98 _ C - _ _ _ _ - _ $\underline{\mathrm{D}}$ _ _ -
Form C, 5 amps , minimum off-state impedance: $20 \mathrm{~K} \Omega$


Electromechanical Relay without Contact Suppression
98 _ C $\qquad$ - _ E $\qquad$
Form C, 5 amps, off-state impedance: $31 \mathrm{M} \Omega$
Solid-state Relay without Contact Suppression
98 _ C $\qquad$ - _ K K _ _ _
0.5 amps , off-state impedance: $31 \mathrm{M} \Omega$

Figure 2.14b - Switched DC, Open Collector 98 _ C - _ _ _ - _ $\underline{C}$

Minimum load resistance: $500 \Omega$


Figure 2.14c - External Signal Conditioner Power Supply 98 _ C _ _ _ _ - _ $\mathbf{T}_{\text {_ }}$

NOTE:


See Chapter 1 for power supply DIP switch information.

For data communications wiring refer to Data Communications with the Watlow Series 988 Family of Controllers.

# Chapter 3 Front Panel and Display Loop 

After 1 minute with no key activations, the control reverts to the Display Loop. The process value appears in the upper display and the set point is in the lower display. For more information on the Display Loop, see the next page.

## Upper Display

Indicates either actual process value, the operating prompt values, or error codes. When powering up, the Process display will be blank for 3 seconds. Red or green, 0.4 " ( 10 mm ) high, seven segment, four digit LED display.

## Dev LED

When lit, the deviation from the current set point is shown in the lower display.

## \% Out LED

When lit, the current percent output is shown in the lower display.

## Up Key

Increases the value of the displayed prompt. A light touch increases the value by one. Holding the key down increases the value at a rapid rate. New data is self entering in 5 seconds or once the Mode key or Display key is pressed.

## Down Key

Decreases the value of the displayed prompt. A light touch decreases the value by one. Holding the key down decreases the displayed value at a rapid rate. New data is self entering in 5 seconds or once the Mode key or Display key is pressed.

## Up + Down Keys

When pressed simultaneously for 3 seconds, the Setup (SEt) prompt appears. Continue to press the Up/Down keys for another 3 seconds and the Factory (Fcty) prompt appears.

Figure 3.1 -
Series 982 Keys and Displays.

## NOTE:

For information on Input 1 In 1 and Input 2 Ine ranges, refer to Chapter 4.

## NOTE:

If $\boldsymbol{n a}$ is selected for InCl, in the Input Menu, the Pr 2 prompt will not appear.

Figure 3.2 The Display Loop.

## Display Loop

The Display Loop is the "home" state of the Series 982 controller. Pressing the Display key $\operatorname{\text {IIsLaN}}$ returns the controller to the Display Loop from any prompt in any menu. The controller automatically returns to the Display Loop from any menu when a minute passes without any keys being pressed.

|  | 982] current input 1 reading |
| :---: | :---: |
|  | 982 set point 1 (change with Up-arrow and Down-arrow keys) |
| (1spLav | 38.2 current slidewire percent reading |
| - | $\operatorname{Pr} 2$ input 2 process (appears only if controller equipped with slidewire option) |
| ISPLAM | 982] current input 1 reading |
| Isprat $\rightarrow$ | 982 deviation from set point, process 1 minus set point 1 (DEV light on) |
| ISPLAA | 982] current input 1 reading |
|  | IED percent output (\%OUT light on) |
| Arav | 982. current input 1 reading |
| $\longrightarrow$ | ${ }^{\circ} \mathrm{L}$ units selected (units, ${ }^{\circ} \mathrm{F}$ or ${ }^{\circ} \mathrm{C}$ ) |

## Single Set Point

When a program is not running, you can adjust the set point, shown in the lower display, by pressing the Up-arrow or Down-arrow key or through serial communications. You can de-engergize all outputs, including event outputs, by lowering set point 1 to the range low setting minus one, which will display DFF in the lower display.

## Ramping

When a program is running, the set point is controlled by the program. You can view this set point, but cannot change it while the program is running. You can select the event output status for each step.

# Chapter 4 The Setup Menus 

## Navigating the Setup Menus



CAUTION:
When navigating thru Setup Menus, outputs will be disabled.

NOTE:
Press the Display key oisenay to return to the Display Loop from any point in any menu.

Figure 4.1 -
Navigating the Setup Menus.

NOTE:
The lockout DIP switch hides the Setup Menus. See Chapter 1.

To reach the Setup Menus, begin in the Display Loop and press both the Uparrow $\triangle$ and Down-arrow $\square$ keys for three seconds. The Setup Menu prompt SEE will appear in the lower display, and the Input Menu prompt InPE will appear in the upper display. The four Setup Menus are: Input InPE; Output DEPE; Global GLbL; and Communications [DTM. Use the Up-arrow $\triangle$ or Down-arrow key to select a menu and the Mode key mode to step through a menu. The Communications Menu appears only on units equipped with the data communications option.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 982 returns to the Setup Menu prompt SEE. Use the Up-arrow $\triangle$ and Down-arrow $\boxtimes$ keys to select the next menu, or use the Mode key moos to advance through the same menu again. To move backwards through the menu hold the Mode key mods down and press the Uparrow key $\boldsymbol{\sim}$. Use the Up-arrow $\boldsymbol{\sim}$ or Down-arrow key to change the prompt setting.

Refer to the Appendix for model number options. For information about communications and the communications prompts, refer to the supplemental manual Data Communications with the Watlow Series 988 Family of Controllers.

(1) Begin in the Display Loop, and press the Up-arrow $\triangle$ and Down-arrow keys simultaneously to reach the Setup Menus.

(2) Press the Up-arrow key to select one of the Setup Menus.

Reaching the Input Menu

(3) Select the Input Menu, then press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key $\boldsymbol{\sim}$ or the Down-arrow key $\nabla$ to select one of the prompt values.
*Prompts may not appear, depending on controller configuration.


Figure 4.2 -
The Input Menu.

NOTE:
Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1
CEE $\|$ parameter in the Input Menu.

## in 1



CAUTION: Changing the value of in $\boldsymbol{\eta}$ changes most other prompts to the factory default values and clears all program steps. Verify the correct sensor type before making a change. Document all settings before changing sensor type. Failure to follow this guideline could result in damage to equipment or property.

## Pn 1

Input 1 continued on next page.

## Input Prompts

When you are in the Setup menus, the Series 982 displays the menu selection ( INPE, DEPE, GLBL or [GTP] ) in the upper display, and SEE in the lower display.

The Up-arrow $\boldsymbol{\square}$ or Down-arrow key selects another menu. Press the Mode key moos to display the prompt in the lower display and its value in the upper display. Use the Up-arrow $\boldsymbol{\sim}$ or Down-arrow key to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key moos.

## Input 1

Select sensor type for input 1. This selection must match the sensor type connected to terminals 8, 9 and 10. See Appendix for more information about sensors.

- Changing the value of in $\boldsymbol{f}$ changes all other prompts to the factory default values, except the Communications and Lockout menus, the $[\quad F$ prompt in the Global Menu and the $\quad d F L$ prompt in the Calibration Menu. If you change the value, the default warning $d F L E$ will flash in the upper display.
- Changes do not take effect automatically after five seconds; you must press the Mode key moos to enter the sensor type change and advance to the next prompt.
[n $\boldsymbol{\|}$ This prompt always appears.






thermocouple

thermocouple


## Setup-Input

## in 1

Input 1 continued from previous page.


## Decimal 1

Select the decimal point location for process type input 1 data. This prompt, in conjunction with the Range Low and Range High prompts, allows you to format and limit units of measure for process 1.

- All prompts with units of measure related to input 1 will display in the selected decimal format.
- This affects propbands, alarm set points, process set points, calibration offsets, deadbands and ranges.
$\boldsymbol{d E [} \boldsymbol{\pi}$ This prompt appears only if you have set input 1 in $\boldsymbol{I}$ to a process input.


NOTE:
These values do not affect the low or the high set point limit for process alarms.

## Range Low 1 and Range High 1

Select the low and high limits for input 1. These prompts limit the adjustment range for the set points. The default values are the same as the limits of the sensor you selected by setting the input 1 DIP switch and selecting a value for Input 1 in $\boldsymbol{n}$.

- Process inputs are scaled by these values. Range high is the value displayed when the maximum process signal is present at the input. Range low is the value displayed when the minimum process signal is present at the input.


## $r[i$ -H

Range Low 1 and Range High 1 continued on next page.

```
Example: Set in t to प-टDmA.
    Set rim to IDD.
    Set rH| to 50D.
    A 4mA input will display IDOD.
    A 12mA input will display 30D.
    A 20mA input will display 50D.
```



```
A 4mA input will display [DD].
A 12 mA input will display \(30 \square\).
A 20 mA input will display 50 .
```

- The low and high values of each sensor type are listed on the specifications page of the Appendix.
- Choose between Fahrenheit and Celsius at the $\boldsymbol{C} \boldsymbol{F}$ prompt in the Global Menu.
$\boldsymbol{r} \boldsymbol{I} \boldsymbol{r} \boldsymbol{H} \boldsymbol{T}$ These prompts always appear.
 the page of



Range Low 1 and Range High 1 continued from previous page.

NOTE:
These values do not affect the low or the high set point limit for process alarms.

## Calibration Offset 1

Offset the input 1 signal by a positive or negative value. This allows you to compensate for lead resistance, sensor errors or other factors.
[RII This prompt always appears.


## RTD Calibration Curve 1

Select the calibration curve for the RTD 1 input. The RTD input uses either the European (DIN, $0.003850 \Omega / \Omega /{ }^{\circ} \mathrm{C}$ ) or the Japanese (JIS, $0.003916 \Omega / \Omega /{ }^{\circ} \mathrm{C}$ ) linearization standard.

## $\boldsymbol{r E d} \boldsymbol{d}$ This prompt appears only if you have set in $\boldsymbol{f}$ to red or $r$ t.d.



## Software Filter 1

Select the filter time constant, in seconds, for input 1 . This smooths a rapidly changing input signal for display or control purposes.

- Select a positive value to filter only the display.
- Select a negative value to filter the input signal.
- Set the value to $\square$ to disable the filter.

FEr $\boldsymbol{\|}$ This prompt always appears.


## $\ln 2$



CAUTION: Changing the value of inel changes most other prompts to the factory default values and clears all program steps. Verify the correct sensor type before making a change. Document all settings before changing input type. Failure to follow this guideline could result in damage to equipment or property.

NOTE:
If $n a$ is selected for ind none of the other input 2 prompts will appear.

## NOTE:

See Chapter 9 for more information on slidewire feedback.


NOTE:
These values do not affect the low or the high set point limit for process alarms.

## NOTE:

If $[5 L, d]$ is selected for in己, OEC prompt will not appear.

## Input 2

Select sensor type for input 2. This selection must match the sensor type connected to terminals 18, 19 and 20. See Appendix for more information about sensors.

- Changing the value of ine changes all other prompts to the factory default values, except the Communications and Lockout menus, the $[\quad F$ prompt in the Global Menu and the $d F L$ prompt in the Calibration Menu. If you change the value, the default warning dFLE will flash in the upper display.
- Changes do not take effect automatically after five seconds; you must press the Mode key mods to enter the sensor type change and advance to the next prompt.

InC This prompt and other Input 2 prompts appear only on controllers equipped with input 2 hardware (not 98 $\qquad$ $-\quad 0$ $\qquad$
$\qquad$ ).


## Range Low 2

Select the low resistance of the slidewire potentiometer.


## rHe

NOTE:
These values do not affect the low or the high set point limit for process alarms.

## NOTE:

See Chapter 9 for more information on slidewire feedback.

## Lral

## LraH

Range High 2

Select the high resistance of the slidewire potentiometer.
rH2 This prompt appears only on controllers with In己 (Input Menu) set to [5L id.


## Learn Low

Write the low-end resistance of the slidewire potentiometer to the range low 2 parameter.

LraL This prompt appears only on controllers with In己 (Input Menu) set to [5L id.

| Default |  |
| :---: | :---: |
| $\downarrow$ |  |
| na |  |
| Lral | Lral |

## Learn High

Write the high-end resistance of the slidewire potentiometer to the range low 2 parameter.

set to [5L , d.

## [RLC

## Calibration Offset 2

Offset the input 2 signal by a positive or negative value. This allows you to compensate for lead resistance, sensor errors or other factors.
[RID This prompt appears only on controllers with In己 (Input Menu) set to SLid.


## Hurt Hunt

NOTE:
See Chapter 9 for more information on slidewire feedback.

Set the deadband, as a percentage of output, to keep the valve from hunting.

- The slidewire hysteresis $\mathbf{5 H} 5$ setting provides additional control over a valve.

Hunt This prompt appears only on controllers with Ind (Input Menu) set to SL id.


Figure 4.11 Hunt and slidewire inner hysteresis.

## Slidewire Hysteresis

Set the inner hysteresis, the point at which the valve output turns off.

- The figure below illustrates the interaction between slidewire hysteresis SHYS and hunt Hunt.

SH45 This prompt appears only on controllers with Ind (Input Menu) set to SL id].


## Setup-Output

## Reaching the Output Menu

(1) Begin in the Display Loop, and press the Up-arrow and Down-arrow $\square$ keys simultaneously for three seconds to reach the Setup Menus.

(2) Press the Up-arrow key to select one of the Setup Menus.
(3) Press the Mode key moos to step through the prompts.

(4) Press the Up-arrow key or the Down-arrow key $\boldsymbol{\square}$ to select one of the prompt values.

Figure 4.12 -
Navigating the Output Menu.


## Output Prompts

NOTE:
Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1 CEE $\quad$ parameters in the Input Menu.

When you are in the Setup menus, the Series 982 displays the menu selection ( InPE, DEPE, GLBL or [DFT] in the upper display, and

SEE in the lower display.
The Up-arrow or Down-arrow key selects another menu. Press the Mode key mode to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow $\triangle$ and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key mode.

## Output 1

Set the way that output 1 will respond to a difference between the set point and an input variable.

- HE select reverse action, so that output 1 responds when the input signal is less than the set point.
- $[L$ select direct action, so that output 1 responds when the input signal is more than the set point.

IE $\int$ This prompt always appears.



## Process 1

Select the process range for output 1.
Pref This prompt appears only on controllers equipped with output 1 process hardware (98 $\qquad$ -_F_ $\qquad$ ).

Default

| 4-20mA | 0-20mA | 0-5V= | 1-5V= | 0-10V $=$ (dc) |
| :---: | :---: | :---: | :---: | :---: |
| 4-20] | [-2-2] | $\boldsymbol{B - 5}$ | 1-5 | [-ID |
| Prat | Prct | Pret | Prgi | Pret |

## H45 1 <br> Hysteresis 1

Select the switching hysteresis for output 1. This determines the change in temperature or process units needed to turn the output from full on to full off.

H45 1 This prompt does not appear on controllers equipped with output 1 process hardware ( 98 $\qquad$ -__F F_- $\qquad$ ).


NOTE:
DEC prompt will not appear if [5L id is selected for ine.

## Output 2

Set the way that output 2 will respond to a difference between the set point and an input variable.

- RLC de-energizes output 2 in an alarm condition.
- HLEn energizes output 2 in an alarm condition.
- HE select reverse action, so that output 2 responds when the input signal is less than the set point. This prompt only appears if IUE is set to [LI.
- [L select direct action, so that output 2 responds when the input signal is more than the set point. This prompt only appears if UE $\boldsymbol{\|}$ set to HE.

OEC This prompt appears only on controllers equipped with output 2 hardware (not 98_-__A-__). RLC and RLEn do not appear if output 2 is a process output (98_-__F-__) HE and [D do not appear if [HL $9 \boldsymbol{D}$ (in the Global Menu) is set to $\boldsymbol{\text { IUPL }}$.


## Process 2

Select the process range for output 2.
Prad This prompt appears only on controllers equipped with output 2 process hardware (98_-__F-__) and with ■ED not set to na.
Default
$\downarrow$

| 4-20mA | 0-20mA | 0-5V $=$ | $1-5 \mathrm{~V}=$ | 0-10V $=$ (dc) |
| :---: | :---: | :---: | :---: | :---: |
| 4-3R | [-2B | [ | 1-5 | [-7n |
| Pres | Pres | Pres | Pres | Pres |

## Hysteresis 2

Select the switching hysteresis for output 2. This determines the change in temperature or process units needed to turn the output from full off to full on.

- If RLZ is set to RREE settings for HUS己 will be in degrees per minute or units per minute.
- If the input referenced by RLE is set to red the range is affected as listed below.

HY52 This prompt appears only on controllers equipped with output 2 hardware and with $\boldsymbol{B E} \boldsymbol{Z}$ not set to ag. This prompt does not appear on controllers with $\boldsymbol{\operatorname { l n }} \boldsymbol{Z}$ set to $\mathbf{5 L} \boldsymbol{d}$ or on controllers equipped with output 2 process hardware.

| $\begin{gathered} \text { If } \\ \downarrow \end{gathered}$ |  | Default $\downarrow$ |  |  |
| :---: | :---: | :---: | :---: | :---: |
| OF |  | I | 3 | 999 |
| C-F |  | HYSE | HYSE | HYSE |
| (Giobal Menu) |  |  |  |  |
| OFF \& | red | 1.1 | 30 | 999 |
| [.F | Tnl ${ }^{\text {l }}$ | HYSt | H45E | H4SE |
| (Global Menu) | (nnput Menu) |  |  |  |
| O[ |  | I | ] | 555 |
| - ${ }^{\text {ch }}$ |  | HESE | H4SE | HYSE |
| (Global Menu) |  |  |  |  |
| O[] \& | $r$ E.d | 0.1 | 20 | 55.5 |
| [-F | Inl | H4SE | H4St | H4SE |
| (Global Menu) (Input Menu) |  |  |  |  |
|  |  | $\dagger$ | 3 | 999 |
| a process input is selected |  | HPSE | H4SE | H4SE |

## Alarm 2

Select the alarm type for alarm 2. Select the trigger points for the alarm with the REL $\boldsymbol{B}$ and REH 1 settings in the System Menu 5 S5.

- Pr I uses the process signal from input 1. Changing the set point does not change the alarm response.
- $\boldsymbol{\text { E }} \boldsymbol{f}$ uses a deviation from the input 1 signal. Changing the set point changes the alarm response.
- $\operatorname{rREE}$ uses the rate of change at input 1 in degrees per minute.

RLZ This prompt appears only on controllers equipped with output 2 hardware (not 98 $\qquad$ A $\qquad$ ), and with BL


## Latching 2

Select whether alarm 2 will be latching or non-latching. A latching alarm LAE must be turned off manually. A non-latching alarm al $\boldsymbol{A}$ turns off when an alarm condition no longer exists.

LRE 2 This prompt appears only on controllers equipped with output 2 hardware (not 98 $\qquad$ A $\qquad$



## SHE

See Chapter 8 for more information on alarms.

日E 3

NOTE:
See Chapter 8 for more information on alarms.

## Silencing 2

Select silencing to inhibit alarm 2 on startup and to allow the operator to reset the alarm output, not the visual display.

- Silencing disables the alarm until the signal is between RELD and REH $\quad$.

ALE This prompt appears only on controllers equipped with output 2 hardware (not 98___A-__) and with OEC set to ALC or 日LEn.

| Default |  |
| :---: | ---: |
| $\downarrow$ |  |
| OFF | On |
| SIIFE | EIIIE |

## Output 3

Set the way that output 3 will respond to a difference between the set point and an input variable.

- AL3 de-energizes output 3 in an alarm condition.
- BL $3 \boldsymbol{n}$ energizes output 3 in an alarm condition.
- Ent3 sets output 3 to an event output.

DE 3 This prompt appears only on controllers equipped with output 3 hardware for a relay (98_-__-B__, 98_-__-J__ or $98 \ldots-\quad$-K__ ) or switched dc (98 $\qquad$ -C $\qquad$


## Alarm 3

Select the alarm type for alarm 3.

- Pr $\boldsymbol{\eta}$ uses the process signal from input 1.
- dE 1 uses a deviation from the input 1 signal.
- FAEE uses the rate of change at input 1 in degrees per minute.

AL 3 This prompt appears only on controllers equipped with output 3 hardware for a relay (98_-__-B_, 98_-__-J__ or $98 \ldots-\quad-\mathrm{K} \_$) or switched dc (98_-__C__), and with OEB set to RI 3 or RL Bn.

| Default <br> $\downarrow$ |  |
| :---: | :---: |
| Pr 1 | dEt |
| HL 3 | Hats |

## H457 Hysteresis 3

Select the switching hysteresis for alarm 3. This determines the change in temperature or process units needed to turn the output from full off to full on.

- If RL3 is set to RREE settings for HY53 will be in degrees per minute or units per minute.
- If the input referenced by RL 3 is set to red the range is affected as listed below.

HY53 This prompt appears only on controllers equipped with output 3 hardware for a relay ( 98 $\qquad$ -B $\qquad$ 98 $\qquad$ $-\mathrm{J}$ $\qquad$ or 98_- $\qquad$ $-\mathrm{K}$ ) or switched dc (98 $\qquad$ -C $\qquad$ ) and with $\boldsymbol{A E} 3$ set to PLI or RLBn.


## LAE 3 <br> Latching 3

NOTE:
See Chapter 8 for more information on alarms.

Select whether alarm 3 will be latching or non-latching. A latching alarm LRE must be turned off manually. A non-latching alarm $\boldsymbol{n} \boldsymbol{L} \boldsymbol{A}$ turns off when an alarm condition no longer exists.

LRE 3 This prompt appears only on controllers equipped with output 3 hardware for a relay (98_-__-B__, 98_____J__ or 98_-__-K__) or

Default

| $\downarrow$ |  |
| :---: | :---: |
| nLA | LAE |
| LREB | LREB |

## Silencing 3

Select silencing to inhibit alarm 3 on startup and to allow the operator to reset the alarm output, not the visual display.

- Silencing disables the alarm until the signal is between $\boldsymbol{B H Z} \boldsymbol{B}$ and R3H $\boldsymbol{H}$.

5 II 3 This prompt appears only on controllers equipped with output 3 hardware for a relay (98_-___B__, 98_____J__ or 98____-K__) or


| Default |  |
| :---: | :---: |
| $\downarrow$ |  |
| 日FF | 日n |
| CIIE | 5IIS |

NOTE:
See Chapter 8 for more information on alarms.

## Output 4

Set the way that output 4 will respond to a difference between the set point and an input variable.

- AL 4 de-energizes output 4 in an alarm condition.
- RL4 4 energizes output 4 in an alarm condition.
- Ent 4 sets output 4 to an event output.

DE4 This prompt appears only on controllers equipped with output 4 hardware for a relay (98 $\qquad$ -_B $\qquad$ , 98 $\qquad$
$\qquad$ -_D $\qquad$ 98 $\qquad$ -_E or 98 $\qquad$ -_K__ or switched dc (98_ $\qquad$ -_C__.


## Alarm 4

## Select the alarm type for alarm 4.

- Pr $\boldsymbol{\|}$ uses a process signal from input 1.
- dE $\boldsymbol{A}$ uses a deviation from the input 1 signal.
- $\boldsymbol{r} \boldsymbol{H E E}$ uses the rate of change at input 1 in degrees per minute.

RI 4 This prompt appears only on controllers equipped with output 4 hardware for a relay ( 98 $\qquad$ -_B , 9 $\qquad$ --_D_ , 98 $\qquad$ -_E or 98_____K_) or switched DC (98 _- $\qquad$ -_C ) and BE 4 is set to RLY or HL4n.

Default


| Pri | dE 1 | FREE |
| :---: | :---: | :---: |
| AL4 | AIL 4 | RLU |

## HY54

## Hysteresis 4

Select the switching hysteresis for alarm 4. This determines the change in temperature or process units needed to turn the output from full off to full on .

- If RI 4 is set to rAEE settings for H454 will be in degrees per minute or units per minute.
- If the input referenced by $\boldsymbol{A L} \boldsymbol{4}$ is set to $\boldsymbol{r} \boldsymbol{E} \boldsymbol{d}$ the range is affected as listed below.

H554 This prompt appears only on controllers equipped with output 4 hardware for a relay (98 $\qquad$ -_B $\qquad$ 98 $\qquad$ -_D $\qquad$ , 98 $\qquad$ -_E $\qquad$ or 98______K_) or switched dc (98_-___-_C_) and with OE 4 set to RL 4 or HL 4n.

NOTE:
See Chapter 8 for more information on alarms.

## LREY

NOTE：
See Chapter 8 for more information on alarms．

## Latching 4

Select whether alarm 4 will be latching or non－latching．A latching alarm LRE must be turned off manually．A non－latching alarm nLR turns off when an alarm condition no longer exists．

LRE 4 This prompt appears only on controllers equipped with output 4
 switched dc（98＿＿＿＿＿C＿）and with OUY set to RLY or RL4n．
Default
$\downarrow$
GLA
LREY LRE
LREY

## Silencing 4

Select silencing to inhibit alarm 4 on startup and to allow the opera－ tor to reset the alarm output，not the visual display．
－Silencing disables the alarm until the signal is between $\boldsymbol{R} 4 \boldsymbol{\square} \boldsymbol{\square}$ and ［日4 H］

5 IL 4 This prompt appears only on controllers equipped with output 4 hardware for a relay（98＿＿＿＿－＿B＿，98＿＿＿＿＿－D＿，98＿＿＿＿＿－＿＿or 98＿＿＿＿＿K＿）or switched DC（98＿＿＿＿＿＿C＿）and with ロ早4 set to PLL 4 or PL 4n．

| Default |  |
| :--- | ---: |
| $\downarrow$ |  |
| DFF | 日n |
| SIIG | SIIS |

## Rout

NOTE:
See Chapter 9 for more information on retransmit.

## Analog Output

## Select which value to retransmit as the output 3 signal.

- Prc\| retransmits the process 1 value.
- SEPE retransmits the set point.
- Prad retransmits the process 2 value. This prompt appears only if the controller is equipped with input 2 hardware and if inc is not set to nal or $E$, ㄹ.
- na turns off retransmit function.

Hout This prompt appears only on controllers equipped with retransmit hardware (98 $\qquad$ -M $\qquad$ or 98 $\qquad$ -N $\qquad$
Default
$\downarrow$
Pred SEPE Pred no
Rowt Rout Rout Rout

## Process 3

Select the range for the retransmit signal at output 3.
Pra3 This prompt appears only on controllers equipped with retransmit hardware (98 $\qquad$
$\qquad$ -M $\qquad$ or 98 $\qquad$ -N $\qquad$ ) and with Rout not set to

## no.

| Default$\downarrow$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |
| 4-20mA | 0-20mA | $0.5 \mathrm{~V}=$ | $1-5 \mathrm{~V}=$ | $0-10 \mathrm{~V}=$ (dc) |
| 4-2D] | [-2] | [-5 | 1-S | [ $-\boldsymbol{T}$ |
| Pret | Pret | Prat | Pret | Prct |

NOTE:
See Chapter 9 for more information on retransmit.

ArH

## Retransmit Low Limit

Select the low limit for the retransmit signal at output 3.

- The default value is equal to $r \boldsymbol{L} \boldsymbol{f}$ or $\boldsymbol{r} \boldsymbol{Z}$ (in the Input Menu) depending on whether Rout is set to Pred or Pred.
$\boldsymbol{A r} \boldsymbol{L}$ This prompt appears only on controllers equipped with retransmit hardware (98 $\qquad$ -M $\qquad$ or 98 $\qquad$
$\qquad$ $-\mathrm{N}$ $\qquad$ ) and with Rout not set to na.

| -999 |  |
| :---: | :---: |
| Rri | RrH |
| Rri |  |

## Retransmit High Limit

Select the high limit for the retransmit signal at output 3.

- The default value is equal to $\boldsymbol{r} \boldsymbol{H} \boldsymbol{f}$ or $\boldsymbol{r} \boldsymbol{H} \boldsymbol{Z}$ (in the Input Menu) depending on whether Raut is set to Pret or Pred.
$\boldsymbol{A r} \boldsymbol{H}$ This prompt appears only on controllers equipped with retransmit hardware (98 $\qquad$ -M $\qquad$ or 98 $\qquad$
$\qquad$ -N $\qquad$ J and with Rout not set to


## na.

```
Frl
    ArH

\section*{Retransmit Calibration Offset}

Select an offset value for the retransmit signal at output 3.
HIPI This prompt appears only on controllers equipped with retransmit hardware (98 \(\qquad\)
\(\qquad\) \(-\mathrm{M}\) or 98
\(\qquad\)
\(\qquad\) \(-\mathrm{N}\) \(\qquad\) ) and with Rout not set to

\section*{na.}


\footnotetext{
is selected
}

\section*{Reaching the Global Menu}
(1) Begin in the Display Loop, and press the Up-arrow \(\boldsymbol{C}\) and Downarrow \(\square\) keys simultaneously for three seconds to reach the Setup Menus.
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{4}{|l|}{} \\
\hline inPt & DtPE & 9LbL & [DFワ \\
\hline 5EE & 5EE & 5Et & 5Et \\
\hline Input & Output & Global & Communications \\
\hline Menu & Menu & Menu & Menu \\
\hline p. 4.2 & p. 4.12 & p. 4.28 & p. 4.38 \\
\hline
\end{tabular}
(2) Press the Up-arrow key to select one of the Setup Menus.
(3) Press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key \(\boldsymbol{\sim}\) or the Down-arrow key \(\boldsymbol{\square}\) to select one of the prompt values.
\(\rightarrow\) GLbit Global Menu

*Prompts may not appear, depending on controller configuration.

\section*{Global Prompts}

NOTE:
Decimal points may not always be in the position specified below depending on the the settings in the Decimal 1 CEE I parameters in the Input Menu.


NOTE:
For more information on errors, see Chapter 8.

When you are in the Setup menus, the Series 982 displays the menu selection ( InPE, DEPE, GLBL or [DPT) in the upper display, and SEE in the lower display.

The Up-arrow \(\boldsymbol{\sim}\) or Down-arrow key selects another menu. Press the Mode key moos to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow \(\boldsymbol{\square}\) keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key mode.

\section*{Celsius-Fahrenheit}

Select which temperature scale the controller will use.
[_F This prompt appears only on controllers with in \(\boldsymbol{I}\) set to something other than a process input.


\section*{Error Latching}

Select whether alarms will be latching or non-latching.
- Non-latching alarms \(\boldsymbol{n} \boldsymbol{L} \boldsymbol{A}\) turn off when there is no alarm condition.
- Latching alarms LRE must be turned off manually.

Err This prompt always appears.


\section*{Event Input 1}

Select the effect of closing the event input 1 switch.
- \(\boldsymbol{n} \boldsymbol{a}\) disables event input 1.
- LDI locks out the front panel keys.
- Rll resets an alarm.
- DFF turns all control outputs off (de-energize relays, but does not hold program).
- Hold puts the controller into hold mode (ends the program and holds the last set point).

- RBSP controls to the abort set point.
- PRUS pauses a running profile.
- LIE can be configured as a waitfor event input.

E, \(\boldsymbol{I}\) This prompt always appears.
Default
\(\downarrow\)

\(E, ?\)

\section*{Event Input 2}

Select the effect of closing the event input 2 switch.
- \(\quad\) пa disables event input 2 .
- LII locks out the front panel keys.
- RL r resets an alarm.
- DFF turns all control outputs off (de-energize relays, but does not hold program).
- hald puts the controller into hold mode (ends the program and holds the last set point).
- Fil \(\boldsymbol{F}\) ile \(\boldsymbol{F}\) il 3 or \(\boldsymbol{F}\) i! \(\boldsymbol{4}\) starts file \(1,2,3\) or 4 .
- RBSP controls to the abort set point.
- PRuS pauses a running profile.
- LIE can be configured as a waitfor event input.

E , 己 This prompt appears only on controllers with event input 2 hardware (98__-5___) and with Ine (Input Menu) set to \(\boldsymbol{E}\), ᄅ].

Default
\(\downarrow\)


Abort Set Point

Select the set point that will take effect when a running profile is aborted with an event input switch.

R65P This prompt appears only on controllers with E , \| or E, I set to RBSP.


\section*{Annunciator}

Select whether alarm messages will flash in the lower display.
Bnun This prompt always appears.
Default
\(\downarrow\)
```

Ba BFF
Bnua Rnum

```

LaP

\section*{Low Power Limit}

Select the low limit for the percent output. For cooling (direct acting) enter a negative number.

LoP This prompt always appears.
\begin{tabular}{|c|c|}
\hline If & Default \(\downarrow\) \\
\hline & - HDP\%.. H, \\
\hline a heat/cool application & LaP LoP \\
\hline & \(\square \% \ldots \boldsymbol{H}\) \\
\hline a heat only application & LoP Lop \\
\hline & - IDR\%... H, \\
\hline a cool only application & LoP LoP \\
\hline
\end{tabular}

\section*{High Power Limit}

Select the high limit for the percent output. For cooling (direct acting) enter a negative number.
\(\boldsymbol{H}, \boldsymbol{P}\) This prompt always appears.
\begin{tabular}{|c|c|c|}
\hline \[
\begin{gathered}
\text { If } \\
\downarrow
\end{gathered}
\] & \multicolumn{2}{|l|}{Default \(\downarrow\)} \\
\hline \multirow[b]{2}{*}{a heat/cool application} & Lop & IDB\% \\
\hline & H,P & H, P \\
\hline \multirow[b]{2}{*}{a heat only application} & Lop & IDB\% \\
\hline & H,P & H, P \\
\hline \multirow[b]{2}{*}{a cool only application} & LoP & \(\square \%\) \\
\hline & H,P & H.P \\
\hline
\end{tabular}

\section*{RESP}

\section*{Auto-tune Set Point}

Select the percentage at which the controller will auto-tune the current control set point.

HESP This prompt always appears.


\section*{Program Type}

Select whether the program type will be time based or ramp rate.
- E selects a time based program.
- FREE selects a program type of ramp rate in degrees or units per minute.

PEYP This prompt always appears.
Default
\(\downarrow\)
E I PREE
PEYP PLYP

\section*{Guaranteed Soak Deviation}

Guarantees that the process temperature or units is maintained within the selected window centered on the set point. If the process temperature or units varies above or below the set point by more than the selected value, the time clock stops and the lower display alternately flashes \(\mathbf{9 5 d}\) and the current parameter until the process variable is again within the window. Setting \(\mathbf{9 5 d}\) to \(\square \boldsymbol{B}\) disables guaranteed soak deviation.

G5d This prompt always appears.


\section*{Power Outage}

Select what will happen when power is lost, then restored. Make sure the backup battery DIP switch is on (see Chapter 1).
- Cant continues running the profile from the point at which it was interrupted.
- HOL \(\boldsymbol{d}\) maintains the set point in effect when the power was interrupted.
- RbrE quits running the profile, displays DFF in the lower display and turns off all outputs.
- Id5P maintains the set point selected at the idle set point prompt IdSP (the next prompt).
- \(\boldsymbol{r}\) SEE resets the program to step 1 .
- If Hald, Bbrt or \(\boldsymbol{H} \boldsymbol{d S P}\) is selected, the lower display alternately flashed Pout and the current parameter. Press \(\frac{\text { Gow }}{\text { GIUN }}\) to clear it.

Prut This prompt always appears.


\section*{Idle Set Point}

Select the set point that will take effect after a power interruption.
IdSP This prompt only appears if Paut is set to IdSP.


NOTE:
Decimal points may not always be in the position specified depending on the the settings in the Decimal 1 dE[ \(\boldsymbol{I}\) parameter in the Input Menu.

\section*{Profile Start}

Select whether the profile starts at the current set point value \(\operatorname{SEPE}\) or the current process value Prag.
- If Paut is set to [ant and PSEr is set to Pract then if power is interrupted the controller will use the current process value as its set point.

PSER This prompt always appears.
Default
\(\downarrow\)
SEPE Prac
PSER PSEr

\section*{Lockout}

\section*{Select the level of operator lockout.}
- \(\quad \boldsymbol{\square}\) no lockout.
- \(\quad\) locks out the PID and Calibration menus and the auto-tune prompt, RHE
- \(\int\) locks out the System, Program, PID and Calibration menus.
- 3 locks out the System, Program, PID and Calibration menus and locks the set point.

LII This prompt always appears.


\section*{Reaching the Communications Menu}
(1) Begin in the Display Loop, and press the Up-arrow \(\triangle\) and Downarrow \(\square\) keys simultaneously for three seconds to reach the Setup Menus.
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{4}{|l|}{} \\
\hline inPt & DLPE & 9LbL & [ \\
\hline 5Et & 5Et & 5Et & 5Et \\
\hline Input & Output & Global & Communications \\
\hline Menu & Menu & Menu & Menu \\
\hline p. 4.2 & p. 4.12 & p. 4.28 & p. 4.38 \\
\hline
\end{tabular}
(2) Press the Up-arrow key \(\boldsymbol{\operatorname { c r }}\) to select one of the Setup Menus.
through the prompts.

(4) Press the Up-arrow key \(\boldsymbol{\rightarrow}\) or the Down-arrow key \(\boldsymbol{\square}\) to select one of the prompt values.

*Prompts may not appear, depending on controller configuration.

NOTE:
The Communications Menu appears only on controllers equipped with communications hardware ( 98 _-___-_R or 98 \(\qquad\) -_S \(\qquad\) 98-\(-\mathbf{U}^{\text {or }}\) ).

See Data Communications with the Series 988 Family of Controllers for detailed information on communications.

Figure 4.38 -
Navigating the
Communications Menu.

\section*{Communications Prompts}

When you are in the Setup menus, the Series 982 displays the menu selection ( InPE, BLPE, GLBL] or [FPT] in the upper display, and SEE in the lower display.

The Up-arrow \(\boldsymbol{\square}\) or Down-arrow key \(\boldsymbol{\square}\) selects another menu. Press the Mode key moos to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow \(\boldsymbol{\square}\) and Down-arrow keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key moob.

\section*{Baud Rate}

\section*{Select the communications speed.}
brifd This prompt appears only on controllers equipped with communications hardware (98_____-R__ or 98_____-_ or 98__-___U__).

Default
\begin{tabular}{|c|c|c|c|c|c|}
\hline 9587 & 308 & 680 & 1288 & [470 & 4808 \\
\hline BRUS & BRHD & BRIUd & BRHD & BRHD & BRHD \\
\hline
\end{tabular}

\section*{Data Bits and Parity}

Select the communications format (start bit = 1, stop bit = 1).
- Setting Prat to FMad automatically sets \(\boldsymbol{D R E R}\) to Ba.
dAER This prompt appears only on controllers equipped with communications hardware (98 \(\qquad\) -_R \(\qquad\) or 98 \(\qquad\) -_S \(\qquad\) or 98 \(\qquad\) -_U__).


\section*{Protocol Type}

Select the communications protocol.
- FIIL \(L\) selects ANSI X3.28 2.2-A.3.
- on selects Xon/Xoff.
- MTad selects Modbus.

Prot This prompt appears only on controllers equipped with communications hardware (98_ \(\qquad\) -_R__ or 98 \(\qquad\) -_S \(\qquad\) or 98 \(\qquad\) -_U__).

Default


FULL Pa Friad
Prat Prat Prat

\section*{Address}

Select an address for the controller. The computer will use this address when communicating with this controller.
fiddr This prompt appears only on controllers equipped with communications hardware for EIA/TIA-485 and EIA/TIA-422 (98 \(\qquad\)
\(\qquad\) \(--S\)
\begin{tabular}{|c|c|c|}
\hline If & Default \(\downarrow\) & \\
\hline 485 & \(\square\) & 31 \\
\hline inter & Rddr & Rddr \\
\hline 422 & \(\square\) & 9 \\
\hline IntF & Hddr & Rddr \\
\hline
\end{tabular}

\section*{Interface Type}

Select the interface type for Output 4，option S．
－ 485 selects EIA／TIA－485．
－पट己 selects EIA／TIA－422．
IntF This prompt appears only on controllers equipped with communi－ cations hardware for EIA／TIA－485 and EIA／TIA－422（98 \(\qquad\)
\(\qquad\) －＿S \(\qquad\)
Default
\(\downarrow\)
485422
intr
InEF

\section*{IntF}

\section*{Interface Type}

Select the interface type for Output 4，option \(U\) ．
－ 485 selects EIA／TIA－485．
－\(己 \exists 己 ⿱ 一 𫝀 口 1 ~ s e l e c t s ~ E I A / T I A-232 . ~\)
\(\operatorname{Bn} E F\) This prompt appears only on controllers equipped with communi－ cations hardware for EIA／TIA－485 and EIA／TIA－232（98 \(\qquad\) －＿U＿＿）．
\begin{tabular}{cc}
\begin{tabular}{c} 
Default \\
\(\downarrow\) \\
\(\downarrow\) \\
2FI \\
IntF
\end{tabular} & \\
\hline IntF \\
\hline
\end{tabular}

Notes

\title{
Chapter 5 The Operation Menus
}

\section*{Navigating the Operation Menus}

To reach the Operation Menus, begin in the Display Loop and press the Mode key moos. The Operation Menu prompt DPEF will appear in the lower display. The three Operation Menus are: System SYS, PID \(\boldsymbol{P}, \boldsymbol{d}\) and Program Prag. Use the Up-arrow \(\boldsymbol{\sim}\) or Down-arrow \(\boldsymbol{\nabla}\) key to select a menu and the Mode key moos to step through a menu.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 982 returns to the Operation Menu prompt DPER. Use the Up-arrow \(\square\) and Down-arrow \(\square\) keys to select the next menu, or use the Mode key mod to advance through the same menu again. To move backwards through the menu hold the Mode key moob down and press the Up-arrow key \(\boldsymbol{\Gamma}\). Use the Up-arrow \(\boldsymbol{\square}\) or Down-arrow \(\boldsymbol{\square}\) key to change the prompt setting.
NOTE:
Press the Display
key oiscan to return to the Display Loop from any point in any menu.

(1) Begin in the Display Loop, and press the Mode key mode to reach the Operation menus DPEr.


Figure 5.1 -
Navigating the Operation Menus.

(2) Press the Up-arrow key to select one of the Operation menus.

\section*{Reaching the System Menu}
(3) Select the System Menu, then press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key \(\boldsymbol{\Delta}\) to step through the prompt values. The Down-arrow key \(\boxtimes\) backs through the values.

*Prompts may not appear, depending on controller configuration.

Figure 5.2 -
The System Menu.

\section*{System Prompts}

NOTE:
Decimal points may not always be in the position specified depending on the setting in the Decimal 1 dEE parameter in the Input Menu.

When you are in the Operations menus the Series 982 displays the menu selection ( 545, P,d or Prag) in the upper display and DPEr in the lower display.

The Up-arrow \(\boldsymbol{\sim}\) or Down-arrow key selects another menu. Press the Mode key mode to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow \(\boldsymbol{\square}\) and Down-arrow \(\boldsymbol{\square}\) keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key modes.

\section*{Event Input 1 Status}

Indicates whether the event input 1 circuit is open or closed. This is a read-only prompt.

E, IS This prompt appears only if E, \| (Global Menu) is set to something other than \(\boldsymbol{n} \boldsymbol{\square}\).

Default
\(\downarrow\)
BPEN [LDS]
E,IS E,IS

\section*{Event Input 2 Status}

Indicates whether the event input 2 circuit is open or closed. This is a read-only prompt.

E , 25 This prompt appears only on controllers equipped with event input
 thing other than na.

Default
\(\downarrow\)
BPEN [LAS
E, ES EICS

Ent3]

\section*{Event Output 3 Status}

Sets event output 3 on or off. When a profile is complete or on hold, it holds at its previous state.

Ent3] This prompt appears only when [IE3] (Output Menu) set to Ent3.

Default \(\downarrow\)

DFF Dn
EnEB EnEB

\section*{Event Output 4 Status}

Sets event output 4 on or off. When a profile is complete or on hold, it holds at its previous state.

EnE 4 This prompt appears only when BE4 (Output Menu) set to Ent 4 .
\begin{tabular}{cc}
\begin{tabular}{c} 
Default \\
\(\downarrow\) \\
\\
DFF \\
EntB
\end{tabular} & \\
& EntB
\end{tabular}

NOTE:
For more information about alarms, see Chapter 8.

\section*{Alarm 2 Low}

Select the low trigger value for the output 2 alarm.

BCLD This prompt appears only if RLC (Output Menu) is set to something other than no.


\section*{Alarm 2 High}

Select the high trigger value for the output 2 alarm.
HCH This prompt appears only if RL己 (Output Menu) is set to something other than na.
\begin{tabular}{|c|c|c|c|}
\hline \[
\begin{aligned}
& \text { If } \\
& \downarrow
\end{aligned}
\] & \multicolumn{3}{|c|}{Default \(\downarrow\)} \\
\hline & & & highest \\
\hline Pril & \multirow[t]{3}{*}{\begin{tabular}{l}
BELD \\
REH
\end{tabular}} & \multirow[t]{2}{*}{\begin{tabular}{l}
value of \\
rHil
\end{tabular}} & value of \\
\hline RLE & & & sensor \\
\hline (Output Menu) & & (Input Menu) & range \\
\hline dE 1 or rREE & \(\square\) & 999 & 9998 \\
\hline RLE BRLE & ALC & REH & ReH! \\
\hline
\end{tabular}
(Output Menu)

\section*{R3LD}

NOTE:
For more information about alarms, see Chapter 8.

R3H
Alarm 3 High

Select the high trigger value for the output 3 alarm.
H3H \(\boldsymbol{H}\) This prompt appears only if RL3 (Output Menu) is set to something other than na.



NOTE:
For more information about alarms, see Chapter 8.

\section*{Alarm 4 Low}

Select the low trigger value for the output 4 alarm.
B4I \(\boldsymbol{B}\) This prompt appears only if RI 4 (Output Menu) is set to something other than no.

(Output Menu)

\section*{Alarm 4 High}

Select the high trigger value for the output 4 alarm.
B4H This prompt appears only if RL 4 (Output Menu) is set to something other than no.


RHE

NOTE:
For more information on auto-tune see Chapter 8.

\section*{Auto-tune}

Initiate an auto-tune.
RUE This prompt always appears.
\begin{tabular}{|c|c|}
\hline Default \(\downarrow\) & \\
\hline DFFF & \(P\) \\
\hline AIIE & Chb \\
\hline
\end{tabular}

\section*{Reaching the PID Menus}
(1) Begin in the Display Loop, and press the Mode key mois to reach the the Operation menus EPEEr.

(2) Use the Up-arrow \(\boldsymbol{C}\) key to select a menu.
(3) Press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key to step through the prompt values. The Down-arrow key backs through the values.

Figure 5.10 -
The PID Menus.


\section*{PID Prompts}

NOTE:
Decimal points may not always be in the position specified depending on the setting in the Decimal 1 dE[ 1 parameter in the Input Menu.

When you reach the Operation menus, the Series 982 displays the menu selection ( 545, P,d or Prag ) in the upper display and DPEr in the lower display.

The Up-arrow \(\boldsymbol{\sim}\) or Down-arrow key selects another menu. Press the Mode key mome to display the first prompt in the lower display and its value in the upper display. Use the Up-arrow \(\triangle\) and Down-arrow \(\square\) keys to change the value in the upper display. The new value will not take effect until after a five-second delay or until you press the Mode key mode.

\section*{Output 1 Proportional Band}

Select the proportional band for PID output 1. If set to \(\quad \square\) it functions as an on/off control, and the switching differential is determined by the HYS \(\boldsymbol{1}\) value (Output Menu).

Pb 1 This prompt always appears.


\section*{rE \(t\) \\ Output 1 Reset}

Tune the control action to eliminate the offset or droop between the set point and the actual process value for PID output 1. When set to IDDI, reset is disabled.
\begin{tabular}{|c|c|c|c|}
\hline \multicolumn{4}{|c|}{\multirow[b]{2}{*}{5}} \\
\hline & & & \\
\hline
\end{tabular}
\begin{tabular}{|c|c|}
\hline Default & \\
\hline DOD & 999 repeats/min \\
\hline ret & \(\square \boldsymbol{T E}\) \\
\hline
\end{tabular}

\section*{Output 1 Integral}

Tune the control action to eliminate the offset or droop between the set point and the actual process value for PID output 1. When set to ODD, integral is disabled.

IE \(\boldsymbol{I}\) This prompt appears only if dFI (Calibration Menu) is set to \(5 \boldsymbol{B}\) and Pb is not set to D.

Default
\(\downarrow\)
DDD ... 99.99 min. / repeat
IEI IEI

\section*{Output 1 Rate}

Tune the rate to eliminate overshoot on startup or after the set point changes. The rate setting will not influence the percent power if the process value is more than twice the proportional band from the set point. When set to [IDE, rate is disabled.


\section*{Output 1 Derivative}

Tune the derivative to eliminate overshoot on startup or after the set point changes. The derivative setting will not influence the percent power if the process value is more than twice the proportional band from the set point. When set to D[DD, derivative is disabled.
```

dE | This prompt appears only if dFL (Calibration Menu) is set to
5|}\mathrm{ \and Pb I is set higher than ■ B
Default
\downarrow
D\#D ... }9.99\mathrm{ min.
dE| dE|

```

\section*{CE}

NOTE:
For more information on burst fire, brSE, see Chapter 9.

\section*{Output 1 Cycle Time}

Select the time, in seconds, of a complete on/off cycle.
[EI This prompt appears only if In ! (Input Menu) is not set to a process and \(\boldsymbol{P} \boldsymbol{B} \boldsymbol{\|}\) is set higher than \(\square \boldsymbol{\square}\).


Pbel

\section*{Output 2 Proportional Band}

Select the proportional band for PID output 2. If set to \(\quad \square\) it functions as an on/off control and the switching differential is determined by the HYSㄹ value (Output Menu).

PBE This prompt appears only if BE (Output Menu) is set to HE or CL.


\section*{Output 2 Reset}

Tune the control action to eliminate the offset or droop between the set point and the actual process value for PID A output 2. When set to DOD, reset is disabled.
\(\boldsymbol{r E E}\) This prompt appears only if \(\boldsymbol{d F} \boldsymbol{L}\) (Calibration Menu) is set to \(\boldsymbol{H S}\) and PbC is set higher than D. When set to DOD, reset is disabled.
\begin{tabular}{|c|c|}
\hline \begin{tabular}{l}
Default \\
\(\downarrow\)
\end{tabular} & \\
\hline 100] & 999 repeats/min. \\
\hline ren & rED \\
\hline
\end{tabular}

\section*{Output 2 Integral}

Tune the control action to eliminate the offset or droop between the set point and the actual process value for PID output 2. When set to OUD, integral is disabled.
\(\boldsymbol{I E} \boldsymbol{C}\) This prompt appears only if \(\boldsymbol{d F} \boldsymbol{I}\) (Calibration Menu) is set to \(5 \boldsymbol{7}\) and PbI is set higher than \(\boldsymbol{D}\)
\begin{tabular}{|c|c|}
\hline Default \(\downarrow\) & \\
\hline ODOD & 9999 \\
\hline IEC & IEC \\
\hline
\end{tabular}

\section*{Output 2 Rate}

Tune the rate to eliminate overshoot on startup or after the set point changes. The rate setting will not influence the percent power if the process value is more than twice the proportional band from the set point. When set to DOD, rate is disabled.
\(\boldsymbol{r} \boldsymbol{R} \boldsymbol{P}\) This prompt appears only if \(\boldsymbol{d F} \boldsymbol{L}\) (Calibration Menu) is set to US and Pbe is set higher than ©
\begin{tabular}{|c|c|}
\hline Default & \\
\hline DID & 999 \\
\hline rfer & \(r\) ret \\
\hline
\end{tabular}

\section*{Output 2 Derivative}

Tune the derivative to eliminate overshoot on startup or after the set point changes. The derivative setting will not influence the percent power if the process value is more than twice the proportional band from the set point. When set to \(\boldsymbol{Q D D}\), derivative is disabled.

\begin{tabular}{|c|c|}
\hline Default \(\downarrow\) & \\
\hline DHD & 999 min. \\
\hline dEE & - det \\
\hline
\end{tabular}

\section*{[E]}

NOTE:
For more information on burst fire, brSE, see Chapter 9.

\section*{\(d b\)}

NOTE:
Decimal points may not always be in the position specified below depending on the the settings of the Decimal 1 CE[ I or Set Point 1 SP parameter in the Input Menu.

\section*{Output 2 Cycle Time}

Select the time, in seconds, of a complete on/off cycle.
[EC This prompt appears only if [ntil (Global Menu) is not set to [ESCD and PbC is set higher than © D].
\begin{tabular}{|c|c|c|c|c|}
\hline If & & \multicolumn{3}{|c|}{Default \(\downarrow\)} \\
\hline mechanical & & 50 & 100 & 9999 \\
\hline relay & & CEE & CEE & CHE \\
\hline outputs & & & & \\
\hline open collector & BrSt & 1.1 & 18 & 9993 \\
\hline or solid-state & [E] & CEE & CEE & [EE \\
\hline relay outputs & & & & \\
\hline
\end{tabular}

\section*{Dead Band}

Select the width of the zone between the action of the heating output (reverse acting) and the cooling output (direct acting). If you select a positive value the heat and cool outputs cannot be energized at the same time. If you select a negative value, both outputs can be energized at the same time.
\(\boldsymbol{d} \boldsymbol{B}\) This prompt appears only if \(\boldsymbol{P b} \boldsymbol{Z}\) is set higher than \(\boldsymbol{D}\) and one output performs heating action and another performs cooling action.


Notes

\section*{Chapter 6 The Factory Menus}


CAUTION: When navigating thru the Factory Menus, outputs will be disabled.

NOTE:
The Factory Menus will not appear if the hardware lockout DIP is set to on. See Chapter 1 for more information.

NOTE:
The Factory Menus can only be entered when the setup prompt SEE is displayed.

NOTE:
Press the Display
key \(\sin x\) to return to the Display Loop from any point in any menu.

Figure 6.1 -
Navigating the
Factory Menus.

Navigating the Factory Menus
To reach the Factory Menus, begin in the Display Loop and press the Uparrow \(\triangle\) and Down-arrow keys together and hold for three seconds. The SEE prompt will appear in the lower display. Press and hold the Up-arrow \(\triangle\) and Down-arrow \(\triangle\) keys together again for three seconds until the Fcty prompt appears in the lower display. The Factory Menus will not appear if the hardware lockout DIP is set to on. (See Chapter 1 for more information on DIP switch settings.) The two Factory Menus are Diagnostics \(\boldsymbol{d}, \boldsymbol{R} \boldsymbol{I}\) and Calibration [RL. Upon reaching the Factory Menu prompt \(\boldsymbol{F e E Y}_{\boldsymbol{c}}\) use the Up-arrow \(\triangle\) or Down-arrow \(\nabla\) key to select a menu and the Mode key mode to step through a menu.

You will not see every prompt in any of these menus. The unit's configuration and model number determine which prompts appear. After stepping through each menu, the Series 982 returns to the Factory Menu prompt Fct 4 . Use the Up-arrow \(\triangle\) and Down-arrow \(\square\) keys to select the next menu, or use the Mode key moob to advance through the same menu again. To move backwards through the menu hold down the Mode key moos and press the Up-arrow key \(\boldsymbol{\rightarrow}\). Use the Up-arrow \(\boldsymbol{\rightarrow}\) key to change the prompt setting.

(1) Press the Up-arrow \(\triangle\) and Down-arrow \(\boldsymbol{\square}\) keys together and hold until the SEE prompt appears in the lower display. Press and hold again until the FEES prompt appears in the lower display.

(2) Use the Up-arrow key to select one of the Factory Menus.

\section*{Reaching the Diagnostics Menu}

(3 Select the Diagnostics Menu
d ing, then press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key or the Down-arrow key to select one of the prompt values.

In the Diagnostics Menu only the values of © ISP and Equt can be changed.

\section*{difg Diagnostics Menu}

Fct Factory Menus Enter your settings, from the controller's upper display.
dREE Factory Ship Date (page 6.3)

- - Serial Number

AГワb Ambient Temperature


Rent Ambient A/D Count


Figure 6.2 -
The Diagnostics
Menu.

\section*{Factory Ship Date}

Shows the date that the final factory control test was performed. The first two digits represent the week as numbered from l-- to [5]-The second two digits represent the year --94, --95, etc...

CREE This prompt always appears.

\section*{SBFE}

\section*{Software Revision}

Shows the controller's software revision code. This letter should match the software revision code on the cover of the manual that came with your controller; Li and W982-XUMN Rev L00.
[GDFE This prompt always appears.

\section*{Serial Number}

Shows the controller's serial number. The first two letters in the upper display are to indicate that the controller is in serial number mode. The right half of the upper display shows the first two digits of the serial number. The lower display shows the last four digits of the serial number.

\section*{5n34}

5678
This is what the controller with the serial number 0982345678 would display.
[5n-- This prompt always appears.

\section*{Ambient Temperature}

Shows the ambient temperature at the Input 1 terminals. The temperature is shown in \({ }^{\circ} \mathrm{F}\) in the form [DDP regardless of the settings of CE[D, \(\boldsymbol{D F L}\) or [ F F.

Arrib This prompt always appears.

\section*{Rent}

Gnd
 cont?

\section*{Factory Use Only}

These prompts are used only at the factory.
Hent Gnd Ent \(\boldsymbol{f}\) Ente These prompts always appear.

\section*{Inputs 1 and 2 Module Types}
\(1+41\)
Displays which input module is installed in the controller. Please document this value before contacting the factory for technical assistance.

Input Types
- nand No input module
- Es Thermocouple only module
- Eurr Current detect
- GL ed Slidewire module
- UDFF Universal off
- שrEd Universal rtd
- HEch Universal high-gain thermocouple
- HEcL Universal low-gain thermocouple
- שFTu Universal millivolts
- UPra Universal process
- EIC Event input 2

FㅓI IE Y E These prompts always appear. document this value before contacting the factory for technical assistance.

Output Types
- חanE no output module
- [55 \(\boldsymbol{T}\) 0.5A solid-state relay
- 55150.5 A solid-state relay with suppression
- [5SC] 2.0A solid-state relay
- 5SES 2.0A solid-state relay with suppression
- ds switched dc output
- rlyn form C relay
- rLeS form \(C\) relay with suppression
- FLAB relay \(A / B\)
- \(\boldsymbol{r} \boldsymbol{A B S}\) relay A/B with suppression
- Prac process output
- UREE voltage/retransmit
- IFEE current/retransmit
- [5PLY power supply
- CBE EIA/TIA-232 communications
- 485 EIA/TIA-485 or EIA/TIA-422 communications


\section*{d ISP}

\section*{Eaut}

\section*{Test Displays}

Runs a brief test of the controller's displays and LEDs. To run the test, scroll through the Diagnostics Menu until \(\boldsymbol{d} \boldsymbol{P}\) is shown in the lower display. Use the Up-arrow key or Down-arrow key to select पES from the upper display and press the mode key moos.

The controller will run pattern tests, blink all the LEDs on and off, and end with the model number in both displays.
d ISP This prompt always appears.
\begin{tabular}{cc}
\begin{tabular}{c} 
Default \\
\(\downarrow\)
\end{tabular} & \\
no & पESS \\
CIISP & CIISP
\end{tabular}

\section*{Test Outputs}

This prompt tests each output. To run the test, scroll through the Diagnostics Menu until Equt is shown in the lower display. Use the Uparrow key \(\boldsymbol{\square}\) or Down-arrow key to select an output qut f, qut? [uE3], or quE 4. The LED for that output should light after a second or two indicating that the output has been successfully energized. Do not press the mode key mons to activate the test; it starts automatically when anything other than \(\square F F\) is selected.

If any of the LEDs fail to light contact the factory.
Equt This prompt always appears.
Default
\(\downarrow\)
DFF gut g gute guts buty
Eout Eout Eout Eout Eout

\section*{Reaching the Calibration Menu}
(1) Begin in the Display Loop, and press the Up-arrow \(\boldsymbol{\square}\) and Down-arrow key simultaneously for six seconds until the Setup Menu SEE, then the Factory Menu Fct 4 appears.
(2) Use the Up-arrow key \(\boldsymbol{\sim}\) or Downarrow key \(چ\) to step through the Factory Menu to the Calibration Menu [RIL.

(3) Press the Mode key mode to step through the prompts.

(4) Press the Up-arrow key \(\boldsymbol{\sim}\) or the Downarrow key to select one of the prompt values.

Refer to Calibrating Watlow Process Controls for information about the Calibration Menu.


CAUTION:
Before attempting to calibrate, make sure you have the proper equipment called for in each procedure. The Series 982 is calibrated and tested before it leaves the factory. Attempting to calibrate the controller without the proper equipment could result in damage to property and/or equipment.


Figure 6.7 -
The Calibration Menu.

\section*{Restore}

Restores the original factory calibration values. This is a simple way to recover from a mistake made while calibrating the controller.
\(\boldsymbol{r} \boldsymbol{S E}\) This prompt always appears.


\section*{Default}

Set the operating parameter defaults to domestic or international measures.
- HS (domestic) sets the controller to \({ }^{\circ} \mathrm{F}\); rate in minutes; proportional band in degrees or units; and reset in repeats per minute.
- 5 (international) sets the controller to \({ }^{\circ} \mathrm{C}\); derivative in minutes; proportional band in percent of span; and integral in minutes per repeat.
dFI This prompt always appears.
\begin{tabular}{|c|c|}
\hline Default & \\
\hline W5 & 51 \\
\hline [dFT & dFt. \\
\hline
\end{tabular}

\section*{Chapter 7 The Run Menu}

\section*{How to Program and Run the Series 982}

In this chapter, we define each parameter of the Program Menu. A description of a few Series 982 features follows, along with a sample profile to experiment with programming the Series 982 . You will quickly grasp the necessary terms and concepts by programming and running your profiles. Enter your profile values in the Master Step Chart at the end of the chapter.

\section*{Program Menu}

Create your ramp and soak profiles here in the Program menu. You have the choice of up to four profiles with up to six steps each. Each step can be programmed for one of five step types. Choose one step type per step.

\section*{Program Prompts}

Entering the program menu: Push the Mode key until the OPEr prompt appears. Use the Up or Down key to select Prog in the upper display. Press the Mode key to enter the Program menu.


File: Represents the profile to be edited or viewed.
\begin{tabular}{ll} 
Range: & 1 to 4 \\
Default: & 1
\end{tabular}

Step: Represents the current step of the profile to be edited or viewed. Range: \(\quad 1\) to 6
Default: 1 then automatic increment

\section*{Program Menu}

\section*{NOTE:}

Decimal points may not always be in the position specified depending on the value of Decimal 1 in the Input Menu.

Step Type: Choose from five different step types. When selecting Step 1, you will not see the jump-loop (JL) or link file (LFiL) step type.
Range: StPt, SoAh, JL, LFiL or End
Default: End

\section*{Set Point Step (StPt) : The following parameters are associated with the set point step.}

Set Point: The temperature the system tries to achieve for this step. This is done linearly, producing a ramp from a beginning set point to this end set point.
Range: rL1 to rH1
Default: \(\quad 75^{\circ} \mathrm{F} / 24^{\circ} \mathrm{C}\) or rL value if \(\mathrm{rL} \geq 75^{\circ} \mathrm{F} / 24^{\circ} \mathrm{C}\) or if \(\mathrm{rH} \leq 75^{\circ} \mathrm{F} / 24^{\circ} \mathrm{C}\)
Hour: The number of hours, plus the Min and SEC parameters equal the total step time to achieve the temperature under the StPt step type.
Range: 0 to 99
Default: 0
Hidden if: \(\quad\) PtYP \(=\) rAtE
Minutes: The number of minutes plus the Hour and SEC parameters equal the total step time to achieve the temperature under the StPt step type.
Range: 0 to 59
Default: 0
Hidden if: \(\quad \mathrm{PtYP}=\mathrm{rAtE}\)
Seconds: The number of seconds plus the Hour and Min parameters equal the total step time to achieve the temperature under the StPt step type.
Range: 0 to 59
Default: 0
Hidden if: \(\quad \mathrm{PtYP}=\mathrm{rAtE}\)
Rate: Represents the rate at which the set point changes in degrees per minute. Decimal point location dependent on dEC1 (decimal 1) prompt.
Range: \(\quad 0.0\) to \(360.0^{\circ} \mathrm{F} / 0.0\) to \(200.0^{\circ} \mathrm{C}\) or 0.0 to 360.0 units
Default: 0.0
Hidden if: \(\quad \mathrm{PtYP}=\mathrm{ti}\)
Event 3: Selects whether Event 3 is on or off.
Range: On or OFF
Default: OFF
Hidden if: Hardware not present or Ot3 = AL3, AL3n or no

Enty

\section*{Howr}

5EC

Event 4: Selects whether Event 4 is on or off.
Range: On or OFF
Default: OFF
Hidden if: Hardware not present or Ot4 \(=\) AL4, AL4n or no
Soak: The following parameters are associated with the soak step.

Hour: The number of hours plus the Min and SEC parameters equal the total step time at temperature under the SoAH step type.
\begin{tabular}{ll} 
Range: & 0 to 99 \\
Default: & 0
\end{tabular}

Minutes: The number of minutes plus the Hour and SEC parameters equal the total step time at temperature under the SoAH step type.
Range: \(\quad 0\) to 59

Default: 0

Seconds: The number of seconds plus the Hour and Min parameters equal the total step time at temperature under the SoAH step type.
Range: \(\quad 0\) to 59
Default: 0
Event 3: Selects whether Event 3 is on or off. Only appears if Ot3 = Ent3.
Range: On or OFF
Default: OFF
Hidden if: Hardware not present or Ot3 = AL3, AL3n or no
Event 4: Selects whether Event 4 is on or off. Only appears if Ot4 = Ent4.
Range: On or OFF
Default: OFF
Hidden if: Hardware not present or Ot4 \(=\) AL4, AL4n or no
Waitfor Event Input: The program will wait at this step until the desired status of the event is satisfied. Selecting dSbL disables this feature. See Chapter 7.
Range: dSbL, On or Off
Default: dSbL
Hidden if: Eil and Ei2 not equal to WE
Waitfor process crossover value: The program will wait at this step until the desired process value is reached. If gSd is greater than zero the closest edge of the guaranteed soak band is the process crossover value. Selecting dSbl disables this feature. If time also entered, countdown will not begin until WPr has been satisfied. See Chapter 7 .
Range: \(\quad \mathrm{dSbl}, \mathrm{rL} 1\) to rH1
Default: dSbL

IL


Jump-loop Step (JL) : The following parameters are associated with the jump-loop step. When StEP = 1, JL will not appear.

Jump File: Jumps to the selected file and step (see Jump Step, below), when the jump file value is not equal to current file. If the jump file value equals the current file, only steps less than the current program step are valid selections for a jump step. Changing the jump file value defaults the jump step to 1 . This is a zero-time step.
Range: \(\quad 1\) to 4
Default: current file
Jump Step: Jumps backwards to any step in your file, if the jump file value equals the current file (see Jump File, above). Otherwise you can jump to any valid step number. This is a zero-time step.
Range: \(\quad 1\) to 6
Default: 1
Jump Count: The number of times the Series 981/982 jumps to the step specified by the JS (jump step) parameter. \(0=\) infinite number of jumps.
Range: 0 to 255
Default: 0

Link File (LFiL): The following parameter is associated with the link file step. When StEP \(=1\), LFiL will not appear.

End Step (End) : The following parameter is associated with the end step.

End: Selects the state of the control and auxiliary outputs when a profile is ended. When HoLd is selected, the control and auxiliary outputs are enabled and maintain the same state as in the last set point and/or soak step before the End step was encountered. When selected as OFF, the control and auxiliary outputs will be disabled and OFF is shown in the lower display.
Range: HoLd or OFF
Default: HoLd

\section*{Running a Series 982 Profile}

You can run your Series \(981 / 982\) profile from anywhere except the Setup menus or Factory menus or when the control is auto-tuning. Press the Hold/Run key once. The RUN LED begins flashing, and the lower display flashes FiLE and asks what FiLE is to be run. Use the Up or Down keys to select the file number in the upper display, choices are 1, 2, 3, or 4. Press the Mode key and the lower display flashes StEP and asks what StEP is to be run. Use the Up or Down keys to select the StEP number in the upper display, choices are 1 through 6. Press the Hold/Run key once again, your profile begins, and the RUN LED is lit. If you decide not to run a profile, press the Display key to exit the Pre-Run menu.

If the none of the keys are pressed within 1 minute, the RUN function will abort. While the profile is Running, you can only view the RUN menu. Press the Mode key to advance you through the RUN menu. For more information on the RUN menu see Chapter 7.

\section*{Resume a Profile}

To resume a halted profile, press the Hold/Run key once. Press the Mode key to advance to the rESU parameter. The lower display will show rESU and the upper display will show the file and step number that will be resumed (file-step). Press the Hold/Run key again, the profile resumes, and the RUN LED is lit. You can only resume at the exact step you left off on. If you halt a running profile and make changes, you cannot resume the profile. The rESU parameter only appears when a running profile is halted.

To Run your profile... Press the Hold/Run key twice.
To Stop a running profile... Press the Hold/Run key once.
To Resume a halted profile... Press the Hold/Run key, press the Mode key to advance to the rESU parameter, and press the Hold/Run key.

\section*{Pre-Run and Run Menus}

The Pre-Run and Run menus are only visible when in the Pre-Run or Run mode. The Pre-Run mode is defined as the mode during which the file and step number of the program to run is selected and consists of the FiLE, StEP and rESU prompts. The FiLE and StEP prompts are also visible in the Run menu showing the current file and step number. The remaining prompts in the Run menu show the status of the process, the program being run and the auxiliary outputs. The Display key functions in the Run mode as it does in the Hold mode. The Display key will return the display to the process/current set point display and can be used to display pertinent information about the process.

Figure 7.6 The Pre-Run and Run Menus.

\section*{Event Outputs}

One of the features of the Series \(981 / 982\) is its capability for two event outputs. An "event output" is simply a pre-programmed ON/OFF event per profile step. The event may turn any number of peripheral devices ON or OFF to assist you in controlling your process, system or environment.

For instance, in an environmental chamber, you might wish to circulate air at a given time in your profile for one or more steps. You might want to turn lights on or off, or signals, or lock out your humidifier, or you could activate a video recorder.

The event output prompts, Ent3 and Ent4, are not visible under the Operation menu unless your unit has outputs 3 and 4 and you setup Ot3 and Ot4 as events.

To select outputs 3 and 4 as events, enter the Setup menu by pressing the Up/Down keys simultaneously for 3 seconds. The SEt parameter appears in the lower display. Press the Up or Down key until OtPt is shown in the upper display. Press the Mode key until you reach the Ot3 parameter. The default for Ot3 is AL3 (alarm 3). Change the value to Ent3 (event 3) if it hasn't already been done. Press the Mode key to continue on to the Ot4 parameter. Do the same for this parameter also. Press the Display key to exit the Setup menu.

If you return to the System menu, Ent3 and Ent4 are visible, and can be turned on or off from here. Ent3 and Ent4 can also be viewed under the StPt (Set Point) and SoAH (Soak) parameters in the Program Menu. Select the correct jumper for contact closed with event ON (NO) or contact open with event ON (NC). See Chapter 8.

\section*{Guaranteed Soak Deviation}

The Series 981/982 Guaranteed Soak Deviation (gSd) feature insures that the actual temperature tracks a programmed profile within a window around set point. See the example below. If the deviation is exceeded, the time clock stops and the lower display alternately flashes gSd and the current parameter until the process variable returns within the window. Programmed in degrees or units, gSd is located in the Setup-gLbL menu. Entering a value of (0) disables the Guaranteed Soak Deviation function. Entering a value greater than zero sets up a plus and minus deviation about set point.

Jump-loops

Figure 7.7 Guaranteed Soak Deviation Window around Set Point.


The Series 981 /982 can only jump backwards within the same profile if JF equals the current program profile. A jump forces you to a step already performed. The Jump Step (JS) must be less than the current step. You cannot jump-loop to the step that you are on.

Example:
\begin{tabular}{llll} 
Step 1 & StPt Step & & \\
Step 2 & StPt Step & & \\
Step 3 & Soak Step & & \\
Step 4 & StPt Step & & \\
Step 5 & Jump-loop & JS - 2 & JC - 1 \\
Step 6 & End & &
\end{tabular}

In this example the program will execute steps 2 through 4 a total of 2 times. This includes the initial pass and the pass associated with the Jump Count of \(1(\mathrm{JC}-1)\). Following the second pass the End step (Step 6 ) will be executed and the program will end.

Your Jump Count (JC) can be anything from 0 to 255 . If you enter 0 , this will be an infinite loop and never progresses to Step 6.

When Jump File is not set to the current program step, the profile may jump to any step of another file. In this example Jump File enables the profile to jump between two files.

\section*{Programming a Ramping Profile}

Figure 7.8 -
Using Jump File.


This is a sample program. Depending on your application and parameter settings, your system may not respond like this.

Our first step in programming is to make a short ramp and soak profile. Step 1 initializes the set point to a known starting point for the ramp, Step 2 is a short ramp, and Step 3 is a soak step, which holds the programmed set point constant for the programmed time. Step 4 is an end step signaling the end of the profile.
1. Enter the Operation menu by pressing the Mode key until OPEr appears in the lower display. Use the Up or Down key to select Prog in
the upper display. Press the Mode key to enter the Program menu.
2. The Series 981 /982 asks you for a FiLE. The upper display reads 1 . Press the Mode key to select file 1.
3. The Series \(981 / 982\) asks you for a StEP. The upper display reads 1 .
4. Press the Mode key to select step 1 and you are asked for a step type (StyP). The default is End. Use the Up or Down key to select StPt (set point).
5. Use Table 7.9 to enter the corresponding parameters and values. The parameters appear from left to right on the table. Remember that the Mode key is used to progress through the menu, and the Up and Down keys are used to select parameters and values.

NOTE: If auxiliary outputs are not present or Ot3 and Ot4 are selected as alarms, the Ent3 and Ent4 parameters will not appear in the program
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|}
\hline Step \# & \begin{tabular}{c} 
StyP \\
(Step Type)
\end{tabular} & Set Point & Hour & Min & SEC & Ent3 & Ent4 & WE & WPr & End \\
\hline 1 & StPt & 75 & 0 & 0 & 1 & OFF & OFF & -- & -- & -- \\
\hline 2 & StPt & 100 & 0 & 0 & 25 & On & OFF & -- & -- & -- \\
\hline 3 & SOAH & -- & 0 & 0 & 25 & ON & OFF & dSbl & dSbL & -- \\
\hline 4 & End & -- & -- & -- & -- & -- & -- & -- & -- & OFF \\
\hline
\end{tabular}
menu. If Event Input 1 or 2 is not selected as a waitfor event, the WE
Table 7.9 -
Sample Program.

Figure 7.9 -
Ramp and Soak Profile.
parameter will not appear in the program menu.

\section*{Running Your Profile}

Step 4: an end step, set point to off

Step 3: a soak step, holds set point at \(100^{\circ} \mathrm{F}\)
1. Start your profile by pressing the Hold/Run key. You can be at any point except in the Setup or Factory menus or with the control in the auto-tune mode.
2. The Run LED begins flashing. The upper display shows the file number to be run and the bottom display shows the FiLE parameter.
3. Press the Mode key, the upper display shows the step number to be run and the bottom display shows the StEP parameter.
4. Press the Hold/Run key again. (If not pressed within approximately 1 minute, the Run procedure will abort.) The profile starts running.

The Run LED is continually lit. The upper display shows the process value, and the lower display shows the current set point.

You may step through the Run menu parameters with the Mode key while the profile is running. The Run menu will show the file number, step number, the step type and what the parameters are set to. At any time you may press the Hold/Run key to stop the profile. To resume running the profile where it was stopped, press the Hold/Run key once; the Run LED begins flashing. Now, press the Mode key to advance to the rESU parameter; once again, press the Hold/Run key. After the profile has ended the Run LED is off and the lower display reads OFF. This means the End step was selected as OFF, disabling all outputs.

\section*{Editing Your Profile}

Now let's try editing the profile by expanding it with another ramp step, adding a jump-loop and allowing the program to end in a Hold mode. It is possible to expand the number of steps in a file to 7 if the final step can be an End-Hold step. We'll jump to Step 2 and repeat Steps 2 through 5 two more times. This is accomplished by programming a Jump Step \((\mathrm{JS})=2\) and Jump Count \((\mathrm{JC})=2\). This means that once the Series 981/982 goes through the profile and reaches Step 6 it jumps back to Step 2 and repeats the profile two more times (Steps \(2-5\) ). The program then ends and holds the set point and event status of the last step of the profile prior to ending the program.

By this time you should understand the basic concept of the Series 981/982 and be able to get around on your own. Remember that the Mode key takes you through the menus and the Up/Down keys select parameters and values.
1. Return to the Program menu by selecting Prog at the OPEr prompt. Press the Mode key.
2. Press the Mode key again and select 4 when StEP appears. We are going to change this step type from an End step to a Set Point step. This is our second ramp. Use Table 7.11 to enter values into the corresponding parameters.
3. Once you have edited your profile, run it again and watch its progress.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline Step \# & \begin{tabular}{c} 
StyP \\
(Step Type) \()\)
\end{tabular} & Set Point & Hour & Min & SEC & Ent3 & Ent4 & WE & WPr & JF & JS & JC \\
\hline 4 & StPt & 125 & 0 & 0 & 25 & OFF & On & - & - & - & - & - \\
\hline 5 & SoAH & - & 0 & 0 & 25 & On & OFF & - & - & - & - & - \\
\hline 6 & JL & - & - & - & - & - & - & - & - & 1 & 2 & 2 \\
\hline
\end{tabular}

Table 7.11 -
Editing your Profile.


Figure 7.11 -
Ramp/Soak with
Jump-loop.

\section*{Linking Profiles}

The Series 981/982 enables you to link files together. The Link step allows you to link any step other than the first step of a profile to the first step of another profile.

Let's edit the profile again by adding a Link step to the end of File 1 in place of the Jump-loop step. But first lets create another profile by programming profile 2. Follow Table 7.12 to add a Link step to File 1 to link it to File 2.

Run your program again beginning with File 1. Step through the Run menu by using the Mode key. See what happens at the end of File 1.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline File \# & Step \# & \begin{tabular}{c} 
StyP \\
(Step Type)
\end{tabular} & \begin{tabular}{c} 
Set \\
Point
\end{tabular} & Hour & Min & SEC & Ent3 & Ent4 & WE & WPr & LFIL & End \\
\hline 1 & 6 & LFiL & - & - & - & - & - & - & - & - & 2 & - \\
\hline 2 & 1 & StPt & 175 & 0 & 0 & 25 & On & On & - & - & - & - \\
\hline 2 & 2 & SoAH & - & 0 & 0 & 25 & On & On & - & dSbL & - & - \\
\hline 2 & 3 & StPt & 100 & 0 & 0 & 25 & On & OFF & - & - & - & - \\
\hline 2 & 4 & SoAH & - & 0 & 0 & 25 & On & OFF & - & dSbL & - & - \\
\hline 2 & 5 & StPt & 75 & 0 & 0 & 25 & OFF & OFF & - & - & - & - \\
\hline 2 & 6 & End & - & - & - & - & - & - & - & - & - & Hold \\
\hline
\end{tabular}

Table 7.12 -
Linking Profiles.


Figure 7.12 -
Linking Profiles.

\section*{The Waitfor Functions of the Soak Step}

In the previous profiles we have used the Soak step but have not used the waitfor function for this step. There are two waitfor functions. The first being the wait for event (WE). If selected as On or OFF the Series 981/982 will wait, the program clock will stop and the profile will be held, until the appropriate action is seen at the event input terminals, closed for ON and open for OFF. If the [WE] parameter is set to disable (dSbL) the function will be ignored. The second waitfor function is wait for process crossover value (WPr). If a value is entered under this prompt the profile will wait at this step until the desired process value is reached.

Both waitfor functions (if enabled) must be satisfied before the time entered in the SoAH step is decremented.
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Step \#} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\(\square\) Step Type}} & \multirow[t]{2}{*}{Set Point} & \multicolumn{3}{|c|}{\multirow[t]{2}{*}{Time}} & \multicolumn{5}{|l|}{Events} & \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Values}} \\
\hline & & & & & & & & On & Off & & Off & & \\
\hline & \(\square\) & StPt & SP & Hour & Min & SEC & Ent3 & & Ent4 & & & & \\
\hline & & & & \multicolumn{8}{|l|}{rAtE} & & \\
\hline & \(\square\) & SoAH & & Hour & Min & SEC & Ent3 & & Ent4 & & & WE & WPr \\
\hline & \(\square\) & JL & & & & & & & & \multicolumn{2}{|l|}{\multirow[t]{3}{*}{JF}} & JS & JC \\
\hline & \(\square\) & LFiL & & & & & & & & & & \multicolumn{2}{|l|}{LFiL} \\
\hline & \(\square\) & End & & & & & & & & & & \multicolumn{2}{|l|}{End} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Step \#} & \multirow[t]{2}{*}{\(\square\)} & \multirow[t]{2}{*}{Step Type} & \multirow[t]{2}{*}{Set Point} & \multicolumn{3}{|c|}{\multirow[t]{2}{*}{Time}} & \multicolumn{5}{|l|}{Events} & \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Values}} \\
\hline & & & & & & & & On & Off & & & & \\
\hline & \(\square\) & StPt & SP & Hour & Min & SEC & Ent3 & & Ent4 & & & & \\
\hline & & & & \multicolumn{8}{|l|}{rAtE} & \multicolumn{2}{|l|}{} \\
\hline & \(\square\) & SoAH & & Hour & Min & ISEC & Ent3 & & Ent4 & & & WE & WPr \\
\hline & \(\square\) & JL & & & & & & & & \multicolumn{2}{|l|}{\multirow[t]{3}{*}{JF}} & JS & JC \\
\hline & \(\square\) & LFiL & & & & & & & & & & \multicolumn{2}{|l|}{LFiL} \\
\hline & \(\square\) & End & & & & & & & & & & \multicolumn{2}{|l|}{End} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Step \#} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{\(\square\) Step Type}} & \multirow[t]{2}{*}{Set Point} & \multicolumn{3}{|c|}{\multirow[t]{2}{*}{Time}} & \multicolumn{5}{|l|}{Events} & \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Values}} \\
\hline & & & & & & & & On & Off & & Off & & \\
\hline & \(\square\) & StPt & SP & Hour & Min & SEC & Ent3 & & Ent4 & & & & \\
\hline & & & & \multicolumn{3}{|l|}{rAtE} & \multicolumn{5}{|l|}{} & & \\
\hline & \(\square\) & SoAH & & Hour & Min & SEC & Ent3 & & Ent4 & & & WE & WPr \\
\hline & \(\square\) & JL & & \multicolumn{8}{|l|}{\multirow[t]{3}{*}{\%}} & JS & JC \\
\hline & \(\square\) & LFiL & & & & & & & & & & \multicolumn{2}{|l|}{LFiL} \\
\hline & \(\square\) & End & & & & & & & & & & \multicolumn{2}{|l|}{End} \\
\hline
\end{tabular}
\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Step \#} & \multirow[t]{2}{*}{\(\square\)} & \multirow[t]{2}{*}{Step Type} & \multirow[t]{2}{*}{Set Point} & \multicolumn{3}{|c|}{\multirow[t]{2}{*}{Time}} & \multicolumn{5}{|l|}{Events} & \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Values}} \\
\hline & & & & & & & & On & Off & & Off & & \\
\hline & , & StPt & SP & Hour & Min & SEC & Ent3 & & Ent4 & & & & \\
\hline & & & & \multicolumn{8}{|l|}{rAtE} & & \\
\hline & \(\square\) & SoAH & & Hour & Min & SEC & Ent3 & & Ent4 & & & WE & WPr \\
\hline & \(\square\) & JL & & & & & & & & \multicolumn{2}{|l|}{\multirow[t]{3}{*}{JF}} & JS & JC \\
\hline & \(\square\) & LFiL & & & & & & & & & & \multicolumn{2}{|l|}{LFiL} \\
\hline & \(\square\) & End & & & & & & & & & & \multicolumn{2}{|l|}{End} \\
\hline
\end{tabular}

\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[t]{2}{*}{Step \#} & \multirow[t]{2}{*}{\(\square\)} & \multirow[t]{2}{*}{Step Type} & \multirow[t]{2}{*}{Set Point} & \multicolumn{3}{|c|}{\multirow[t]{2}{*}{Time}} & \multicolumn{2}{|l|}{Events} & \multirow[b]{2}{*}{Off} & \multirow[t]{2}{*}{} & \multirow[b]{2}{*}{Off} & \multicolumn{2}{|r|}{\multirow[t]{2}{*}{Values}} \\
\hline & & & & & & & & & & & & & \\
\hline & \(\square\) & StPt & SP & Hour & Min & SEC & Ent3 & & Ent4 & & & & \\
\hline & & & & rAtE & & & & & & & & & \\
\hline & \(\square\) & SoAH & & Hour & |Min & |SEC & Ent3 & & Ent4 & & & WE & WPr \\
\hline & \(\square\) & & & & & & & & & JF & & JS & JC \\
\hline & \(\square\) & LFiL & & & & & & & & & & LFiL & \\
\hline & \(\square\) & End & & & & & & & & & & End & \\
\hline
\end{tabular}

Table 7.14 - Master Step Chart.

\title{
Chapter 8 Operation, Tuning, Alarms and Error Codes \\ Auto-tuning (Heat and/or Cool)
}

The Series 981 /982 can automatically tune the PID parameters to fit the characteristics of your particular thermal system.

Before beginning the auto-tune sequence, make sure the AtSP parameter located in the Global menu is at the proper setting. This allows the user to select the tuning set point as a percentage of the current control set point. See Chapter 4 for more information on this parameter. The figure below uses the \(90 \%\) default setting to define the auto-tuning process.

Once the auto-tune sequence has begun, the Output 1 and Output 2 proportional band is set to 0 and the control goes into an ON/OFF mode of control at the set point percentage determined by the AtSP parameter. The displayed set point remains unchanged.

Once the control finishes "learning" the system, it returns to a standard PID control with the PID values automatically set as a result of auto-tuning. Any change in the set point while in auto-tune re-initiates the auto-tune procedure.

Auto-tuning at a Set Point of \(200^{\circ} \mathrm{F}\)

Figure 8.1 -
Auto-tuning Example.

Once auto-tune has begun, the process must cross the auto-tune set point four times within an 80 minute time span for the \(981 / 982\) to successfully complete auto-tune. If this does not happen within the 80 minute time limit, the Series \(981 / 982\) chooses PID values based on the 80 minute tuning cycle performed.

NOTE:
You cannot access the RUt prompt while the controller is in run mode.


CAUTION:
If a mechanical relay or contactor is switching power to the load, a longer cycle time may be desirable to minimize wear on the mechanical componets. Typical life of a mechanical relay is 100,000 cycles.


To start auto-tuning:
1. Press the Mode key until the AUt prompt appears in the lower display.
2. Use the Up Down key to select Pid in the upper display.
3. Press the Display key. While the control is in the tuning mode, the lower display alternately displays the normal information and the tunE prompt. The time between alternations is 1 second.
4. When tuning is complete, the displays return to their previous state and AUt reverts to OFF. The 981/982 installs appropriate PID tuning parameters and saves them in non-volatile memory.

To abort auto-tuning either reset the HUt prompt to OFF, or cycle power off and on. In all cases, aborting auto-tune restores all values to those perevious to auto-tuning.

\section*{Manual Tuning}


For optimum control performance, tune the Series 981/982 to your thenmab system. The tuning settings here are for a broad spectrum of applications; your system may have somewhat different requirements. NOTE: This is a slow procedure, taking from minutes to hours to obtain optimum values.

\section*{NOTE:}

Tune heating outputs at a set point above ambient process value.
Tune cooling outputs at a set point below ambient process value.
NOTE:
1. Apply power to the Series 981 ,982 and enter a set point. Begin with these Operation parameters: \(\mathbf{P b}=1, \mathbf{r E} \boldsymbol{I} \mathbf{t}=0.00, \mathbf{r A} / \mathbf{d E}=0.00, \mathbf{C t}=\) 5.0, AUS \(=\mathrm{OFF}\).
2. Proportional Band Adjustment: Gradually increase \(\mathbf{P b}\) until the upper display process value stabilizes at a constant value. The process value will not be right on set point because the initial reset value is 0.00 repeats per minute. (When \(\mathbf{P b}=0, \mathbf{r E} / \mathbf{t}, \mathbf{r A} / \mathbf{d E}\) and cycle time are inoperative, the 981/982 functions as a simple ON/OFF control.) The HYS prompt determines the switching differential value.
3. Reset/ntegral Adjustment: Gradually increase re, or decrease It until the upper display process value begins to oscillate or "hunt." Then slowly decrease re or increase It until the upper display stabilizes again near set point.
4. Cycle Time Adjustment: Set Ct as required. Faster cycle times sometimes achieve the best system control. See Chapter 9, "Burst Firing," for more information. However, if a mechanical contactor or solenoid is switching power to the load, a longer cycle time may be desirable to
minimize wear on the mechanical components. Experiment until the cycle time is consistent with the quality of control you want. Ct will not appear on units with a process output (Option " F ") or if \(\mathrm{Pb}=0\).
5. Rate Derivative Adjustment: Increase rA/AE to 1.00 minute. Then raise set point by \(20^{\circ}\) to \(30^{\circ} \mathrm{F}\), or \(11^{\circ}\) to \(17^{\circ} \mathrm{C}\). Observe the system's approach to set point. If the load process value overshoots set point, increase rA/AE to 2.00 minutes.

Raise the set point by \(20^{\circ}\) to \(30^{\circ} \mathrm{F}\), or \(11^{\circ}\) to \(17^{\circ} \mathrm{C}\) and watch the approach to the new set point. If you increase rA/dE too much, approach to set point is very sluggish. Repeat as necessary until the system rises to the new set point without overshooting or approaching the set point too slowly.
6. Calibration Offset Adjustment: You may want your system to control to a process value other than the value coming from the input sensor. If so, measure the difference between that process value (perhaps at another point in the system) and the process value showing in the upper display. Then enter the CAL offset value you want. Calibration offset adds or subtracts degrees from the value of the input signal.

\section*{Changing the Output 3 Jumper}

If you have model number 98_ C-_ _ _ - \(\underline{\mathbf{J}}\) _ _ _ , Output 3 can be configured as a Form A (NO and common contact) or Form B (NC and common contact) output. To change the output jumper:

Figure 8.3 Output 3 Jumper Location.

1. Remove the control from the case. Release the two tabs on one side of the control, then release the two tabs on the opposite side. You may need to rock the bezel back and forth several times to release the chassis.

NOTE:
An \(\underline{X}\) applies to Alarm 2, 3 and/or 4.
2. Set the jumper to the position you want. See below for jumper location.
3. Return the control chassis to the case. Be sure you have it oriented correctly. Press firmly, but gently, to seat the chassis.

When you select Form \(A\), the contact is open when power is removed from the control. When selecting Form B, the contact closes when power is removed.

\section*{Using Alarms}

Output 2, 3, and/or 4 of the Series \(981 / 982\) can be selected as alarms. This is accomplished in the Output (OtPt) menu under the Ot2, Ot3, or Ot4 prompt. If ALX is selected, the output is energized in the non-alarm condition and de-energizes the output in the alarm condition. Selecting ALXn reverses this action; the output is then de-energized in the nonalarm condition and energized in an alarm condition.

If the L2, L3 or L4 LED on the front panel is lit, this indicates an alarm condition for Output 2,3 or 4 respectively.

Once you've configured the outputs as alarms, enter the OtPt menu again and select the AL2, AL3 and/or AL4 prompt respectively. These prompts select the type of alarm, process, deviation or rate. Each may be independently set low and high. Choose between process alarm input 1 (Pr1), deviation alarm input 1 (dE1), or rate (rAtE) alarm referenced to Input 1.

A process alarm sets an absolute temperature. When the process exceeds that absolute temperature limit an alarm occurs. A process alarm is independent from set point.

Example: If your set point is \(100^{\circ} \mathrm{F}\) and a process alarm is set at \(150^{\circ} \mathrm{F}\) as the high alarm, and \(50^{\circ} \mathrm{F}\) as the low limit, the high limit trips at \(150^{\circ} \mathrm{F}\), and the low alarm at \(50^{\circ} \mathrm{F}\). If you change the set point, the process alarm limits remain the same.

A deviation alarm alerts the operator when the process strays too far
\begin{tabular}{l|l|c}
\multicolumn{1}{c|}{\begin{tabular}{c} 
Jumper \\
Position
\end{tabular}} & \begin{tabular}{c} 
NO \\
(normally open)
\end{tabular} & \begin{tabular}{c} 
NC \\
(normally closed)
\end{tabular} \\
\hline In Alarm Condition & & \\
\hline Ot \(\underline{X}=A L \underline{X}\) & contacts open & contacts closed \\
\hline Ot \(\underline{X}=A L \underline{X} n\) & contacts closed & contacts open \\
\hline \(\operatorname{In}\) Non-alarm Condition & & \\
\hline Ot \(\underline{X}=A L \underline{X}\) & contacts closed & contacts open \\
\hline \(\operatorname{Ot} \underline{X}=A L \underline{X} n\) & contacts open & contacts closed
\end{tabular}

NOTE:
An \(\underline{X}\) applies to Alarm 2, 3 or 4.

NOTE:
An alarm display will be masked by an error condition or when the controller is in the Calibration or Setup menus.
from set point. The operator can enter independent high and low alarm settings. The reference for the deviation alarm is the set point. Any change in set point causes a corresponding shift in the deviation alarm. Low alarms are set at a negative deviation while high alarms are a positive deviation.

Example: If your set point is \(100^{\circ} \mathrm{F}\) and a deviation alarm is set at \(+7^{\circ} \mathrm{F}\) as the high limit, and \(-5^{\circ} \mathrm{F}\) as the low limit, the high alarm trips at \(107^{\circ} \mathrm{F}\), and the low alarm at \(95^{\circ} \mathrm{F}\). If you change the set point to \(130^{\circ} \mathrm{F}\), the alarms follow the set point and trip at \(137^{\circ} \mathrm{F}\) and \(125^{\circ} \mathrm{F}\).

A rate alarm alerts the operator when the process monitored by Input 1 is increasing at a rate higher than that set by AXHI or decreasing at a rate lower than that set by AXLO. The rate is sampled once a second.

Alarms can be latching or non-latching. When the alarm condition is removed, a non-latching alarm automatically clears the alarm output and alarm message, if one is present. You must manually clear a latching alarm before it will disappear.

An alarm is indicated by the corresponding LED on the front panel, L2, L3 or L4. There may be an alarm message flashing in the lower display, but if the Anun prompt is set to OFF (located in the Global menu), no alarm message is displayed. When an alarm message is displayed, it alternately flashes with the current prompt at a 1 second interval in the lower display.

To clear a latching alarm, first correct the condition then press the Hold/Run key once.

Alarm silencing is available with all alarms. This function overrides the alarm on initial power up. On power up, the alarm message is masked and the appropriate L2, L3 or L4 LED and output reflect a non-alarm condition. The silencing is active until the process has entered the safe region located between the low and high alarm settings. Any future deviation outside this safe region triggers an alarm. If an alarm occurs at this point, the output can be silenced by pressing the Hold/Run key once, but the alarm message is still displayed.

\section*{Error Code E1 and E2 Messages}

Four dashes, "- - -", in the upper display indicate a Series 981/982 error. The lower display will indicate the error code. The controller will be in the Hold mode with both control outputs off. The alarm outputs will be in their alarm state and the associated LED lit.

\section*{EX 1: ADD underflow error}

The Input \(\underline{X}\) A/D circuit is underrange. An open or reversed polarity sensor is the most likely cause. Check the sensor; if the connection is good, and functions properly, call the factory. Make sure the InX prompt matches your sensor.

\section*{EX 2: Sensor underrange error}

The Input \(\underline{X}\) sensor generated a value lower than that allowed for the range of the sensor, or the A/D circuitry malfunctioned. Enter a valid input. The A/D

NOTE: An alarm display will be masked by an error condition or when the controller is in the Calibration or Setup menus.

NOTE:
An \(\underline{X}\) applies to Input 1 or 2.
value is below the range limits, but within the \(A / D\) conversion limits. Make sure the InX prompt matches your sensor.

\section*{EX 3: Sensor overrange error}

The Input \(\underline{X}\) sensor generated a value higher than that allowed for the range of the sensor, or the A/D circuitry malfunctioned. Enter a valid input. The A/D value is above the range limits, but within the A/D conversion limits. Make sure the In \(\underline{X}\) prompt matches your sensor.

\section*{ER3: Ambient Error}

Ambient temperature has gone below \(0^{\circ} \mathrm{C} / 32^{\circ} \mathrm{F}\) or above \(65^{\circ} \mathrm{C} / 149^{\circ} \mathrm{F}\). Refer to the restore prompt in the Calibration Menu (Chapter 6).

\section*{EX 4: AD overflow error}

The Input X A/D circuit is overrange. An open or reversed polarity sensor is the most likely cause. Check the sensor; if the connection is good, and functions properly, call the factory. The A/D input voltage is too high to convert an A/D signal. Make sure the \(\operatorname{In} \underline{X}\) prompt matches your sensor.

\section*{Er4: RAM verification error}

Displayed when an internal RAM failure has occurred. Contact the factory.

\section*{Er5: Non-volatile checksum error}

Displayed when an EEPROM checksum error has been detected. This error will reset all parameters to the factory defaults. Turn the power off then back on again. If the error has not cleared, contact the factory.

\section*{Er9: Configuration error}

An incorrect module has been installed in the control. Contact the factory.

\section*{Error Code Actions}

\section*{- To clear error codes EX1, EX2, EX3, or EX4:}
- If \(\mathbf{E r r}=\mathbf{n L A}\), the error code should clear once the problem is corrected.
- If Err = LAt, correct the problem and cycle power. You can also clear the error by pressing the Up/Down keys to enter the Setup menu, then press the Display key.

\section*{- Error codes Er4, Er5, or Er9 will result in these conditions:}
- The control is in Hold mode with both control outputs OFF.
- The alarm outputs are in their alarm state (de-energized with the LED lit).
- The lower display indicates the error code.
- The upper display indicates "_ _ _ _".
- All keys are inactive.
- With Er5, all prompts return to default values.

Cycle power to the control. If the error is still present contact the factory.

\section*{Chapter 9 Software}
\begin{tabular}{ll} 
Burst Fire & 9.2 \\
Communications & 9.4 \\
Dead Band & 9.6 \\
Digital Event & 9.8 \\
Input Filter & 9.10 \\
Retransmit & 9.12 \\
Slidewire Feedback & 9.14
\end{tabular}


CAUTION:
This feature only works with zerocross solid-state devices. It will not function correctly with random-fire devices.


CAUTION: In single-phase applications the controller should be on the same phase as load.

\section*{Burst Fire}

\section*{Overview}

Variable, time-base burst firing from the Series 982 provides the most even distribution of power with the lowest level of noise generation (RFI). An SSR or SCR firing card translates a command signal into a burst of AC cycles. The output is zero-cross fired, which always allows at least one full AC cycle to pass within the variable time base. Burst firing is the preferred mode to control resistive loads.

The Series 982 detects when the AC sine wave of the load will cross the 0 volt point. It uses this information to switch the load ON or OFF only at a 0 -volt point, minimizing RFI.

The burst fire time base in the Series 982 varies from a maximum 1.66second time base ( 1 -percent output; 1 cycle ON, 99 OFF) down to a 33.3millisecond time base (50-percent output; 1 cycle ON, 1 OFF). The graphs on the next page show how the time base varies with the percent output.

\section*{Requirements}
- This feature only works with zero-cross solid-state devices. It will not function correctly with random-fire devices.
- To enable burst fire the Series 982 must have an open collector or solidstate relay output: controllers with option "B," "C" or "K" selected for output 1 (98_C-_-_-____), output 2 (98_C-__*-___), output 3 (98_C-___-*__ or output 4 ( 98 _C-___-_*_).
- In single-phase applications the controller should be on the same phase as load.
- The time burst is appropriate for fast loads or very tight control. It provides advantages only for PID control, not for ON/OFF control.
- The short time bases used by burst fire makes it incompatible with the heater current feature. The heater current option requires a minimum of 300 milliseconds ON time to get a reading.
- The Series 982 has built in zero-cross detection circuitry, eliminating the need for external firing circuitry to trigger SCR's. The controller will not allow burst fire to be selected if its zero-cross detection circuitry is not functioning.
- The feature is enabled by selecting burst fire br St at the cycle time prompt for the appropriate output in the PID Menu - [EIA, [EIB, [EEA or [ECB.
- Only the 982 and 981 can use the burst fire feature. The low-voltage units ( 984 and 983) cannot use burst firing.


Figure 9.3a-Sine waves of burst fire settings.


Figure 9.3b -

Semiconductor oven with burst fire.

\section*{Sample Application}

A Series 982 controls a heated platen in a semiconductor oven. Previously it used a power control requiring a \(4-20 \mathrm{~mA}\) signal to implement burst-fire control. We have replaced the power control with a Watlow Loyola GPAC with a GCD card that accepts a signal directly from an open-collector output of the Series 982 . This gives smooth control at a lower overall system cost.

\section*{Communications}

\section*{Overview}

The serial communications feature allows the Series 982 family to receive commands from and transmit data to a master device, usually a computer. Any function that can be performed via the front panel, can also be accomplished using a serial communications port, allowing you to operate the controller from a computer and to store process data on a computer.

The Series 982 is available with a choice of serial hardware interfaces. An EIA-232 interface allows for one master (computer) and one controller, with a maximum network length of 50 feet ( 15 meters).

The EIA-485/EIA-422 option equips the controller for a multi-drop interface: up to 32 total network devices with EIA-485 and up to 10 total network devices with EIA-422. Each controller will have its own unique address. The total maximum network length is 4,000 feet ( 1,219 meters). All interfaces are isolated.

To select between EIA-485 or EIA-422, enter the Setup Menus by holding the up-arrow \(\boldsymbol{\sim}\) and down-arrow keys simultaneously until setup

SEE appears in the bottom display. Use the up-arrow key to select the Communications Menu [ IFT. At the interface prompt IntF select between 422 or 485.

Other parameters that must be configured in the Communications Menu [RFT] are the baud rate BRHD, data bits and parity \(\boldsymbol{C H E R}\), protocol Prat, and device address Bddr. The protocol prompt must be set to full (ANSI X3.28 2.2-A3) if multiple devices are used with the EIA-485 or EIA-422 interface. If the full protocol is selected, a device address must be selected at the address prompt. For EIA-232, full FIIL or on \(\boldsymbol{I}\) (XON/XOFF) protocol may be selected.

\section*{Requirements}

Choose which interface your application will use: EIA-232 serial communications (98_C-____R__), or EIA-485/EIA-422 serial communications (98_C-____S__), or EIA-232/EIA-485 serial communications (98_C-___U__. The computer must have a compatible serial port or an appropriate converter must be used.


Figure 9.5 - Test chambers with communications.

\section*{Sample Application}

A test engineer uses Series 982s to control the temperatures of several automated test chambers. His computer is linked to the controllers through its EIA-422 serial communications port. His computer program monitors the temperatures of the chambers and initiates automatic test sequences when certain program parameters are met. After completing a sequence, the computer loads the next temperature profile to the controller. The computer periodically interrogates each controller for its process temperature, set point and alarm status. This information is stored on a disk to provide test verification data for the completed products.

\section*{Dead Band}

\section*{Overview}

The dead band prompt, db, located in the PID Menu, determine the amount of interaction between heat (reverse acting) and cool (direct acting) control outputs. The dead band directly offsets the target set point of the cool control output.

With a positive dead band, both control outputs will never be ON at the same time. With the process in a positive dead band, the output value is determined by adding the percent heat output to the percent cool output and only applying the result to the correct output - cooling action if the sum is negative and heating action if it is positive.

If the dead band is set to a negative value, the heat and cool outputs can both be ON at the same time.

\section*{Requirements}

The dead band feature is standard on any Series 982 controller with two control outputs. The dead band prompt will appear if the control outputs are configured for heat/cool or cool/heat.


Figure 9.7a Dead band graph.


Figure 9.7b Environmental chamber with dead band.

\section*{Sample Application}

An engineer for an environmental chamber manufacturer, who is designing the heating and cooling system for a new chamber, wants to minimize the energy costs of operating the chamber. She has chosen the Series 982 and will configure the heat and cool outputs with a positive dead band.

When the chamber temperature is near ambient the cooling and heating systems had a tendency to buck one another, resulting in inefficient use of energy. The engineer started with a dead band of five degrees, but in the process of tuning the system for optimal control, the setting was reduced to two degrees. This made the chamber more energy efficient and reduced wear on the refrigeration system.

\section*{Digital Events}

\section*{Overview}

The digital event input options on the Series 982 controller allow the operator to select one of several software functions with the close of a cus-tomer-supplied switch or by a change in DC voltage (See Chapter 2 for voltage and wiring information.).

The list below outlines the functions that can be controlled with a digital event input:
- Front panel lockout LII locks out the front panel keys to prevent tampering.
- Alarm reset RLr resets alarms from a remote location.
- Turn control outputs off BFF inhibits the control outputs, does not hold program.
- Hold program HoLd ends the program that is currently running and maintains the last set point.
- Start file 1 F IL \(\boldsymbol{I}\) starts file 1 from a remote location. It will have no effect if a file is aready running.
- Start file \(2 \boldsymbol{F}\) II \(己\) starts file 2 from a remote location. It will have no effect if a file is aready running.
- Start file \(3 \boldsymbol{F}\) IL 3 starts file 3 from a remote location. It will have no effect if a file is aready running.
- Start file \(4 \boldsymbol{F} \boldsymbol{\|} \boldsymbol{4}\) starts file 4 from a remote location. It will have no effect if a file is aready running.
- Satisfy a waitfor event input LUE during a soak step.
- Pause PRUS switches the currently running program to hold mode until the event input opens.
- Abort RBSP terminates the currently running program and goes to Abort Set Point.

\section*{Requirements}

A single digital event input is standard on all controls. A second digital input is available as an option for input 2 ( 98 _C-_5____).


Figure 9.9 Heater with digital event.

\section*{Sample Application}

A manufacturing engineer is designing a test chamber that must be very simple for the operator to use. He would like to start the program with minimal operator interaction.

By connecting an external switch to the digital event input, he can configure the Series 982 to start the program in File 1, when the switch momentarily closes. Enable this function by selecting File \(1 \boldsymbol{F} \boldsymbol{\|} \boldsymbol{\|}\) for Event Input 1 E \(\boldsymbol{\|}\) (Global Menu). Once the program is started, closing this switch will not have any effect until the program has finished or the program is terminated.

The operator must also have the ability to pause a running program and then resume it again with the same simple interaction.

By ordering the optional second digital event input, another switch can be used to pause the program when the switch is closed and resume running the program when the switch is opened again. Enable this function by selecting pause PRUS for Event input 2 E, 己 (Global Menu). This function is only active once a program has been started.

The operator now has the ability to start a program with the press of a button, and pause or resume it with the flip of a switch. The operator never needs to touch the Series 982.

\section*{Input Filter}

\section*{Overview}

In certain applications the process being measured can be unstable, which makes it difficult to control and also makes the constantly changing display difficult to read. The Series 982 input filter can solve these problems by smoothing out just the display or the display and the input signal.

You can set a time constant in seconds for a low-pass filter that will, if you select a positive value, affect the display only. Select a negative value to filter the input signal itself. Use this feature with caution, because a large time constant could hide system upsets.

\section*{Requirements}

This feature is standard on all Series 982 controllers.



Figure 9.11a -
Display readings with input filter-
ing.


Figure 9.11b Humidity chamber with input filtering.

\section*{Sample Application}

A Series 982 controls the temperature in an environmental chamber. The sensor is very sensitive to changes caused by air flow in the chamber. The turbulence in the chamber makes the controller display jump two to three degrees. To remove this display dithering set the filter time constant FERI for input 1 to two seconds. This will smooth the display and provide a more realistic reading.

\section*{Retransmit}

\section*{Overview}

The retransmit feature can be used to transmit an analog signal representing the value of either input process variable or the target set point variable. The retransmit signal is factory configured as either a milliamp (98_C- \(\qquad\) -M \(\qquad\) ) or a voltage (98_C- \(\qquad\) \(-\mathrm{N}\) \(\qquad\) ) signal. In choosing the type of retransmit signal the operator must take into account the input impedance of the device or devices to be retransmitted to and the required signal type, either voltage or milliamps.

Typically applications might use the retransmit option to record one of the variables with a chart recorder or to generate a set point for other controls in a multi-zone application.

\section*{Requirements}

Output 3 is used for the retransmit option. Choose either a milliamp (98_C- \(\qquad\) -M__) or a voltage (98_C- \(\qquad\) \(-\mathrm{N}\) \(\qquad\) ) signal. Select the output range in the Output Menu.


Figure 9.13 -Heat-treat oven with retransmit.

\section*{Sample Applications}

An engineer needs to control the temperature of individual zones in an eight-zone furnace. The temperatures range from \(0^{\circ} \mathrm{C}\) to \(850^{\circ} \mathrm{C}\). The process requires the same time/temperature profile for each zone. She wants to do this without using a seperate ramping control for each zone.

The Series 982 can be configured with a milliamp retransmit output for output 3, (98_C- \(\qquad\) -M \(\qquad\) ). This controller can control one zone and provide a common \(4-20 \mathrm{~mA}\) set-point signal for seven Series 988 controllers with remote-set-point capabilities.

Enable the retransmit output by setting Rout to SEPE (Output Menu). This selects the set point as the retransmit variable. To select the retransmit output range, set \(\operatorname{PrcB}\) to \(\mathbf{4 - 2 \boldsymbol { D }}\). The retransmit output is now 420 mA . \(\operatorname{Rr} \boldsymbol{L}\) and \(\operatorname{Ar} \boldsymbol{H}\) determine the scaling for the retransmit output. To make a 4 mA signal represent \(0^{\circ}\), set \(\boldsymbol{\operatorname { A r }} \boldsymbol{L}\) to \(\boldsymbol{D}\). To make a 20 mA signal represent \(850^{\circ}\), set \(\boldsymbol{\operatorname { H r }} \boldsymbol{H}\) to \(\boldsymbol{B 5 D}\). A retransmit calibration offset RLAL is also available, which applies only to the retransmit output.

The retransmit output will be 4 mA until the set point is greater than \(0^{\circ} \mathrm{C}\) and will increase linearly until reaching 20 mA , when the set point equals \(850^{\circ} \mathrm{C}\). The output will not exceed 20 mA .

As the Series 982 changes its set point, the \(4-20 \mathrm{~mA}\) retransmit signal follows it, providing the remote set point signal for the seven Series 988 controllers.

The furnace now can provide ramp and soak capabilities for all eight zones, yet reduce system costs and complexity by using a single ramping controller and seven remote-set-point controllers.

\section*{Slidewire Feedback}

\section*{Overview}

The Series 982 can control the position of a valve with a slidewire feedback position indicator. The controller senses the resistance of the slidewire and compares it to the range low and range high settings to determine the valve position. The controller compares this to the percent output and takes action to match the two by opening or closing the valve.

Set the hunt Hunt parameter to limit valve hunting. The value is set for the percent of output ( 0.0 to 100.0). When the valve is within this dead band, a change in output greater than half the hunt parameter is required to trigger action. If the valve's momentum causes it to "coast" after the contact opens, try increasing the 【HYS value. This determines the turnoff point. Output 1 responds to "close" commands and output 2 responds to "open" commands.

\section*{Requirements}

A slidewire configuration uses at least two inputs and two control outputs. Input 2 must be a slidewire input (98_C-_3 \(\qquad\) ). Outputs must be compatible with the slidewire valve actuators.


Figure 9.15-
Gas-fired furnace with slidewire feedback.

NOTE:
See Chapter 4 for more infromation about Slidewire Hysteresis and Hunt.

\section*{Sample Application}

A Series 982 controls the gas valve for a gas-fired furnace to heat treat large metal parts. First the controller must be "married" to the slidewire feedback from the valve actuator. To do this, first set the Input 2 prompt Ind to slidewire [5L ,d. Advance to the Learn Low Resistance prompt Lrat. Close the valve manually to the minimum resistance reading from the slidewire. Select YES in the upper display and press the Mode key mons to advance to the Learn High Resistance prompt LraH. Manually open the valve (maximum slidewire resistance). Select \(4 E 5\) in the upper display and press the Mode key moobs. At this point both the high and low resistance values have been learned and stored in the range low 2 and range high 2 parameters.

You can also manually set the range low and range high values. From the slidewire specifications, determine the low and high resistance values and enter these at the Range Low ricl and Range High r \(\boldsymbol{H} \boldsymbol{C}\) prompts.

\section*{\(r \mathrm{HC}\) must be greater than \(r \boldsymbol{r}\) 己}

Once the control is operating, adjust the hunt Hunt parameter, to minimize valve oscillations. The hunt parameter sets up a dead band on both sides of the current valve position. The desired valve position is then compared to the actual position. If the difference is greater than one-half of the hunt value, the Series 982 repositions the valve to achieve the temperature set point. Once repositioning is complete, the dead band is recalculated for the new valve position. If your valve opens and closes quickly, try increasing the Hunt value. If the valve's momentum causes it to "coast" after the contact opens, try increasing the [5H55 value.
9.16 WATLOW Series 982 User's Manual

\section*{Warranty}

The Watlow Series 982 is warranted to be free of defects in material and workmanship for 36 months after delivery to the first purchaser for use, providing that the units have not been misapplied. Since Watlow has no control over their use, and sometimes misuse, we cannot guarantee against failure. Watlow's obligations hereunder, at Watlow's option, are limited to replacement, repair or refund of purchase price, and parts which upon examination prove to be defective within the warranty period specified. This warranty does not apply to damage resulting from transportation, alteration, misuse, or abuse.

\section*{Watlow Controls}

Watlow Controls is a division of Watlow Electric Manufacturing Company, St. Louis, Missouri, a manufacturer of industrial electric heating products, since 1922. Watlow begins with a full set of specifications and completes an industrial product that is manufactured totally in-house, in the U.S.A. Watlow products include electric heaters, sensors, controls and switching devices. The Winona operation has been designing solid state electronic control devices since 1962, and has earned the reputation as an excellent supplier to original equipment manufacturers. These OEMs depend upon Watlow Controls to provide compatibly engineered controls which they can incorporate into their products with confidence. Watlow Controls resides in a 100,000 square foot marketing, engineering and manufacturing facility in Winona, Minnesota.

\section*{Returns}
1. Call Watlow Customer Service, (507) 454-5300, for a Return Material Authorization (RMA) number before returning any item for repair. We need this information:
- Ship to address - Bill to address
- Contact name
- Phone number
- Ship via - Your P.O. number
- Symptoms and/or special instructions
- Name and phone number of person returning the material.
2. Prior approval and an RMA number, from the Customer Service Department, is needed when returning any unused product for credit. Make sure the RMA number is on the outside of the carton, and on all paperwork returned. Ship on a Freight Prepaid basis.
3. After we receive your return, we will examine it and determine the cause for your action.
4. In cases of manufacturing defect, we will enter a repair order, replacement order, or issue credit for material. A 20 percent restocking charge is applied for all returned stock controls and accessories.
5. If the unit is unrepairable, it will be returned to you with a letter of explanation. Repair costs will not exceed 50 percent of the original cost.

\section*{Shipping Claims}

When you receive your Watlow control, examine the package for any signs of external damage it may have sustained enroute. If there is apparent damage either outside the box or to its contents, make a claim with the shipper immediately. Save the original shipping carton and packing material.
annunciator - A visual display that uses pilot lights to indicate the former or existing condition of several items in a system.
burst fire - A power control method that repeatedly turns on and off full ac cycles. Also called zero-cross fire, it switches close to the zero-voltage point of the ac sine wave. Variable-time-base burst fire selectively holds or transits ac cycles to achieve the desired power level. See zero cross.
calibration offset - An adjustment to eliminate the difference between the indicated value and the actual process value.
closed loop - A control system that uses a sensor to measure a process variable and makes decisions based on that feedback.
cold junction - see junction, cold.
cold junction compensation - Electronic means to compensate for the effective temperature at the cold junction.
default parameters - The programmed instructions that are permanently stored in the microprocessor software.
derivative - The rate of change in a process variable. Also known as rate. See PID.
derivative control (D) - The last term in the PID control algorithm. Action that anticipates the rate of change of the process, and compensates to minimize overshoot and undershoot. Derivative control is an instantaneous change of the control output in the same direction as the proportional error. This is caused by a change in the process variable (PV) that decreases over the time of the derivative (TD). The TD is in units of seconds.

Deutsche Industrial Norm (DIN) - A set of technical, scientific and dimensional standards developed in Germany. Many DIN standards have worldwide recognition.

DIN - See Deutsche Industrial Norm.
droop - In proportional controllers, the difference between set point and actual value after the system stabilizes.
duty cycle - The percentage of a cycle time in which the output is on.
external transmitter power supply - A dc voltage source that powers external devices.
filter, digital (DF) - A filter that slows the response of a system when inputs change unrealistically or too fast. Equivalent to a standard resistor-capacitor (RC) filter.
form A - A single-pole, single-throw relay that uses only the normally open (NO) and common contacts. These contacts close when the relay coil is energized. They open when power is removed from the coil.
form B - A single-pole, single-throw relay that uses only the normally closed (NC) and common contacts. These contacts open when the relay coil is energized. They close when power is removed from the coil.
form C - A single-pole, double-throw relay that uses the normally open (NO), normally closed (NC) and common contacts. The operator can choose to wire for a form \(A\) or form \(B\) contact.
hysteresis - A change in the process variable required to re-energize the control or alarm output. Sometimes called switching differential.
integral - Control action that automatically eliminates offset, or droop, between set point and actual process temperature. See autoreset.
integral control (I) - A form of temperature control. The I of PID. See integral.
isolation - Electrical separation of sensor from high voltage circuitry. Allows use of grounded or ungrounded sensing element.

JIS - Joint Industrial Standards (JIS) A Japanese agency that establishes and maintains standards for equipment and components. Also known as JISC (Japanese Industrial Standards Committee), its function is similar to Germany's Deutsche Industrial Norm (DIN).
junction, cold - Connection point between thermocouple metals and the electronic instrument. See junction, reference.
junction, reference - The junction in a thermocouple circuit held at a stable, known temperature (cold junction). Standard reference temperature is \(32^{\circ} \mathrm{F}\left(0^{\circ} \mathrm{C}\right)\).

NEMA 4X - A NEMA specification for determining resistance to moisture infiltration. This rating certifies the controller as washable and corrosion resistant.
on/off controller - A temperature controller that operates in either full on or full off modes.
open loop - A control system with no sensory feedback.
output - Control signal action in response to the difference between set point and process variable.
overshoot - The amount by which a process variable exceeds the set point before it stabilizes.

P control - Proportioning control.
PD control - Proportioning control with derivative (rate) action.

PDR control - Proportional derivative control with manual reset, used in fast responding systems where the reset causes instabilities. With PDR control, an operator can enter a manual reset value that eliminates droop in the system.

PI control - Proportioning control with integral (auto-reset) action.

PID - Proportional, integral, derivative. A control mode with three functions: proportional action dampens the system response, integral corrects for droop, and derivative prevents overshoot and undershoot.
proportional - Output effort proportional to the error from set point. For example, if the proportional band is \(20^{\circ}\) and the process is \(10^{\circ}\) below set point, the heat proportioned effort is 50 percent. The lower the PB value, the higher the gain.
proportional band (PB) - A range in which the proportioning function of the control is active. Expressed in units, degrees or percent of span. See PID.
proportional control - A control using only the P (proportional) value of PID control.
range - The area between two limits in which a quantity or value is measured. It is usually described in terms of lower and upper limits.
rate - Anticipatory action that is based on the rate of temperature change, and compensates to minimize overshoot and undershoot. See derivative.
rate band - A range in which the rate function of a controller is active. Expressed in multiples of the proportional band. See PID.
reference junction - see junction, reference.
remote - A controller that receives its set point signal from another device called the master.
remote set point - A signal that indicates the set point for the process, and is sent from another device.
reset - Control action that automatically eliminates offset, or droop, between set point and actual process temperature. Also see integral.
automatic reset - The integral function of a PI or PID temperature controller that adjusts the process temperature to the set point after the system stabilizes. The inverse of integral.
automatic power reset - A feature in latching limit controls that does not recognize power outage as a limit condition. When power is restored, the output is re-energized automatically, as long as the temperature is within limits.
manual reset -1 ) A feature on a limit control that requires human intervention to return the limit to normal operation after a limit condition has occurred. 2) The adjustment of a proportional control to raise the proportional band to compensate for droop.

\section*{Glossary, R-Z}
resistance temperature detector (RTD) - A sensor that uses the resistance temperature characteristic to measure temperature. There are two basic types of RTDs: the wire RTD, which is usually made of platinum, and the thermistor, which is made of a semiconductor material. The wire RTD is a positive temperature coefficient sensor only, while the thermistor can have either a negative or positive temperature coefficient.

RTD - See resistance temperature detector.
thermal system - A regulated environment that consists of a heat source, heat transfer medium or load, sensing device and a control instrument.
thermocouple ( \(\mathbf{t} / \mathbf{c}\) ) - A temperature sensing device made by joining two dissimilar metals. This junction produces an electrical voltage in proportion to the difference in temperature between the hot junction (sensing junction) and the lead wire connection to the instrument (cold junction).
thermocouple break protection - The ability of a control to detect a break in the thermocouple circuit and take a predetermined action.
three-mode control - Proportioning control with integral (reset) and derivative (rate). Also see PID.
time proportioning control - A method of controlling power by varying the on/off duty cycle of an output. This variance is proportional to the difference between the set point and the actual process temperature.
transmitter - A device that transmits temperature data from either a thermocouple or a resistance temperature detector (RTD) by way of a two-wire loop. The loop has an external power supply. The transmitter acts as a variable resistor with respect to its input signal. Transmitters are desirable when long lead or extension wires produce unacceptable signal degradation.
zero cross - Action that provides output switching only at or near the zero-voltage crossing points of the ac sine wave. See burst fire.
zero switching - See zero cross.
\% out LED 3.1

\section*{A}

A/D overflow error 8.6
A/D underflow error 8.5
abort set point 4.31
actions, error code 8.6
address 4.40
alarm 24.17
alarm 2 high 5.5
alarm 2 low 5.5
alarm 34.19
alarm 3 high 5.6
alarm 3 low 5.6
alarm 44.22
alarm 4 high 5.7
alarm 4 low 5.7
alarms 8.4-8.5
alarm silencing 8.5
ambient error 8.6
ambient temperature 6.4
analog output 4.25
annunciator 4.32
auto-tune 5.8
auto-tune set point 4.33
auto-tuning 8.1-8.2

\section*{B}
battery backup DIP 1.4
baud rate 4.39
burst fire 9.2-9.3

\section*{C}

Calibration Menu 6.7-6.8
calibration offset 14.6 calibration offset 24.10 celsius-fahrenheit 4.29 communications 9.4-9.5
Communications Menu 4.38-4.42
configuration error 8.6
cycle time, output 15.14
cycle time, output 25.17

\section*{D}
data bits and parity 4.39
date 6.3
dead band 5.17, 9.6-9.7
decimal 14.4
Declaration of Conformity A. 10
default 6.8
derivative, output 15.13
derivative, output 25.16
deviation alarm 8.4
dev LED 3.1
Diagnostics Menu 6.2-6.6
digital event input 12.10
digital event input 22.9
digital events 9.8-9.9

DIP switch
external power supply 1.5
hardware lock/battery backup 1.4
locations and functions 1.3
universal signal input type 1.6
display loop 3.2
display key 3.1
display tests 6.6
down key 3.1

\section*{E}
editing a profile 7.10-7.11
end 7.4
end step 7.4
environmental chamber 9.7
error codes 8.5-8.6
error latching 4.29
event 3
set point step 7.2
soak step 7.3
event 4
set point step 7.2
soak step 7.3
event input 14.30
event input 1 status 5.3
event input 1 wiring 2.10
event input 24.31
event input 2 status 5.3
event output 3 status 5.4
event output 4 status 5.4
event outputs 7.6-7.7
external power supply DIPs 1.5

\section*{F}

Factory Menus 6.1-6.8
file 7.1
front panel 3.1

\section*{G}
gas-fired furnace 9.15
Global Menu 4.28-4.37
guaranteed soak deviation 4.34, 7.7

\section*{H}
hardware lockout DIP switch 1.4
heater with digital event 9.9
heat-treat oven 9.15
high power limit 4.33
hold/run key 3.1
hold/run LED 3.1
hour 7.3
humididty chamber 9.11
hunt 4.10
hysteresis 14.14
hysteresis 24.16
hysteresis 34.20
hysteresis 44.23

\section*{I}
idle set point 4.36
input 14.3
input 1 wiring 2.8
input 1, digital event 2.10
input 24.8
input 2 wiring 2.9
input 2, digital event 2.9
input DIP switches 1.6
input filter 9.10-9.11
Input Menu 4.2-4.11
input module types 6.4
input/output isolation 2.4
installation procedure 2.1-2.3
integral, output 15.12
integral, output 25.15
interface type 4.41

\section*{J}
jump count 7.4
jump file 7.4
jump-loop 7.8
jump-loop step 7.4
jump step 7.4

\section*{L}

L1... L4 3.1
latching 24.17
latching 34.21
latching 44.24
learn high range 4.9
learn low range 4.9
link file 7.4
linking profiles 7.12
lockout 4.37
lower display 3.1
low power limit 4.32

\section*{M}
manual tuning 8.2-8.3
master step chart 7.14
menu overview 1.2
messages, error code 8.5
minutes 7.2, 7.3
mode key 3.1

\section*{N}
non-volatile checksum error 8.6

\section*{0}

Operation Menu 5.1-5.18
output 14.13
output 1 wiring 2.11
output 24.15
output 2 wiring 2.12
output 34.18
output 3 jumper, changing 8.3
output 3 wiring 2.13
output 44.22
output 4 wiring 2.14
Output Menu 4.12-4.27
output module types 6.5
output test 6.6

\section*{P}

PID Menu 5.10-5.18
power outage 4.35
power wiring 2.4
process 14.14
process 24.15
process 34.25
process alarm 8.4
profile, editing 7.10
profile, resuming 7.5
profile, running 7.5, 7.10
profiles, linking 7.12
profile start 4.36
Program Menu 7.1-7.4
program a ramping profile 7.8-7.9
programming 7.1-7.4
program prompts 7.1
program type 4.34
proportional band, output 15.11
proportional band, output 25.14
protocol type 4.40

\section*{R}
ramp and soak profile 7.9
ramping, set point 3.2
ramping profile, program 7.8-7.9
ramp/soak with jump-loop 7.11
RAM verification error 8.6
range high 14.5
range low 14.5
range high 24.9
range low 24.8
rate 7.2
rate alarm 8.5
rate, output 15.13
rate, output 25.16
Re-run Menus 7.6
reset, output 15.12
reset, output 25.15
restore 6.8
resume a profile 7.5
retransmit 9.12-9.13
retransmit calibration offset 4.27
retransmit high limit 4.26
retransmit low limit 4.26
RTD 14.7
RTD, 2 or 3 wire 2.8
Run Menus 7.5-7.6
running a profile \(7.5,7.10\)

\section*{S}
safety information ii seconds 7.2, 7.3
semiconductor oven, burst fire 9.3
sensor installation 2.4
sensor overrange error 8.6
sensor underrange error 8.5
serial number 6.3
set point 3.2, 7.2
set point step 7.2
Setup Menus 4.1-4.42
silencing 24.18
silencing 34.21
silencing 44.24
slidewire feedback 9.14-9.15
slidewire feedback input 2.9
slidewire hysteresis 4.11
soak 7.3
soak step 7.8, 7.13
software filter 14.7
software revision 6.3
step 7.1
step type 7.2
System Menu 5.2-5.9

\section*{T}
technical assistance ii
test chambers 9.5
test displays 6.6
test outputs 6.6
thermocouple or \(0-50 \mathrm{mV} 2.8\)

\section*{U}
universal signal input type DIP
switches 1.6
up key 3.1
upper display 3.1

\section*{W}
waitfor event input 7.3
waitfor functions 7.13
waitfor process crossover value 7.3
wastewater treatment 9.13
wiring 2.4-2.14
wiring \(0-20 \mathrm{~mA}\) and \(4-20 \mathrm{~mA}\) process inputs 2.5
wiring example 2.6
wiring notes 2.7
\begin{tabular}{|c|c|}
\hline \multicolumn{2}{|l|}{A} \\
\hline \multicolumn{2}{|l|}{H.SH6.7} \\
\hline & Rddr address 4.40 \\
\hline \multicolumn{2}{|l|}{[PH \(\boldsymbol{H}^{\text {alarm } 2 \text { high } 5.5}\)} \\
\hline \multicolumn{2}{|l|}{H2ID alarm 2 low 5.5} \\
\hline \multicolumn{2}{|l|}{[3H \(]^{\text {a }}\) alarm 3 high 5.6} \\
\hline \multicolumn{2}{|l|}{R7ID alarm 3 low 5.6} \\
\hline \multicolumn{2}{|l|}{[4]H \({ }^{\text {d }}\) alarm 4 high 5.7} \\
\hline \multicolumn{2}{|l|}{[4ID alarm 4 low 5.7} \\
\hline \multicolumn{2}{|l|}{HBSP abort set point 4.31} \\
\hline \multicolumn{2}{|l|}{[ALAL retransmit calibration offset
\[
4.27
\]} \\
\hline \multicolumn{2}{|l|}{RIL ᄅ alarm 24.17} \\
\hline \multicolumn{2}{|l|}{FII 3 alarm 34.19} \\
\hline \multicolumn{2}{|l|}{Fil 4 alarm 44.22} \\
\hline \multicolumn{2}{|l|}{HГワb ambient temperature 6.4} \\
\hline \multicolumn{2}{|l|}{Heun annunciator 4.32} \\
\hline \multicolumn{2}{|l|}{Rout analog output 4.25} \\
\hline \multicolumn{2}{|l|}{\(\boldsymbol{H r} \boldsymbol{H}\) retransmit high limit 4.26} \\
\hline & \(\boldsymbol{R r L}\) [ retransmit low limit 4.26 \\
\hline \multicolumn{2}{|l|}{RESP auto-tune set point 4.33} \\
\hline \multicolumn{2}{|l|}{RIIE auto-tune 5.8} \\
\hline \multicolumn{2}{|l|}{B} \\
\hline \multicolumn{2}{|l|}{BRHIC baud rate 4.39} \\
\hline \multicolumn{2}{|l|}{Br St burst fire 9.2} \\
\hline \multicolumn{2}{|l|}{C} \\
\hline \multicolumn{2}{|l|}{\multirow[t]{2}{*}{[ LALIE \(\boldsymbol{F}\) calibration offset 14.6}} \\
\hline & \\
\hline \multicolumn{2}{|l|}{[RL \({ }^{\text {L }}\) calibration offset 24.10} \\
\hline \multicolumn{2}{|l|}{[E\| cycle time, output 15.14} \\
\hline \multicolumn{2}{|l|}{[E] cycle time, output 25.17} \\
\hline \multicolumn{2}{|l|}{D} \\
\hline \multicolumn{2}{|l|}{CRER data bits and parity 4.39} \\
\hline \multicolumn{2}{|l|}{[PHEE date 6.3} \\
\hline \multicolumn{2}{|l|}{db dead band 5.17} \\
\hline \multicolumn{2}{|l|}{dE I derivative, output 15.13} \\
\hline & dE2 derivative, output 25.16 \\
\hline \multicolumn{2}{|l|}{[ IE [ \(\boldsymbol{\square}\) decimal 14.4} \\
\hline \multicolumn{2}{|l|}{dFI default 6.8} \\
\hline \multicolumn{2}{|l|}{d 15P test displays 6.6} \\
\hline \multicolumn{2}{|l|}{\(E\)} \\
\hline \multicolumn{2}{|l|}{E, I event input 14.30} \\
\hline \multicolumn{2}{|l|}{\(\boldsymbol{E}, \mathbf{I S}\) event input 1 status 5.3} \\
\hline \multicolumn{2}{|l|}{E IC] event input 24.31} \\
\hline \multicolumn{2}{|l|}{[ \(\mathbf{1}\), 5 ] event input 2 status 5.3} \\
\hline \multicolumn{2}{|l|}{End end step (end) 7.4} \\
\hline \multicolumn{2}{|l|}{EnE3 event 3 7.2, 7.3} \\
\hline \multicolumn{2}{|l|}{[Ent3 event output 3 status 5.4} \\
\hline \multicolumn{2}{|l|}{EnE4 event 4 7.2, 7.3} \\
\hline \multicolumn{2}{|l|}{EnE4 event output 4 status 5.4} \\
\hline & Errer error latching 4.29 \\
\hline
\end{tabular}

\section*{F}

F,IE file 7.1
FEr \(\boldsymbol{H}\) software filter 14.7

\section*{G}

G5d guaranteed soak deviation 4.34

\section*{H}
\(\boldsymbol{H}, \boldsymbol{P}\) high power limit 4.33
Hour hour 7.2, 7.3
Hunt hunt 4.10
HY5 \(\boldsymbol{1}\) hysteresis 14.14
HYSㄹ hysteresis 24.16
HYS3 hysteresis 34.20
HS54 hysteresis 44.23

\section*{I}

TISP idle set point 4.36
In \(\boldsymbol{1}\) input 14.3
Ind input 24.8
IE \(\boldsymbol{I}\) integral, output 15.12
IEC integral, output 25.15
IEY \(\boldsymbol{D}\) input 1 module type 6.4
-E Y [ input 2 module type 6.4
InEF interface type 4.41
```

J

```

IIT jump count 7.4
UF jump file 7.4
IL jump-loop step 7.4
- IS jump step 7.4

L
[REC] latching 24.17
[REB] latching 34.21
LREG latching 44.24
LF IL link file 7.4
LDI lockout 4.37
L ©P low power limit 4.32
LraH learn high range 4.9
Lral learn low range 4.9

\section*{M}
[7. \(\boldsymbol{\Gamma}\) minutes 7.2, 7.3

BE \(\boldsymbol{D}\) output 14.13
DEC output 24.15
- DE 3 output 34.18

DE 4 output 44.22
[DE 4 ] output 1 module type 6.5

DE Y ㄹ output 2 module type 6.5
[DE Y 3 output 3 module type 6.5
DEY4 output 4 module type 6.5

\section*{P}

PRIIS pause 9.8
Pb \(\boldsymbol{P}^{2}\) proportional band, output 1 5.11

PbI proportional band, output 2 5.14

Paut power outage 4.35
Pre\| process 14.14
Prect process 24.15
Pre3 process 34.25
PSET profile start 4.36
PEYP program type 4.34
Prot protocol type 4.40

\section*{R}
\(\boldsymbol{r} \boldsymbol{R} \boldsymbol{\eta}\) rate, output 15.13
\(\boldsymbol{r} \boldsymbol{R E D}\) rate, output 25.16
FREE rate 7.2
rEI reset, output 15.12
rED reset, output 25.15
\(\boldsymbol{r} \boldsymbol{H} \boldsymbol{I}\) range high 14.5
r HC range high 24.9
FLI range low 14.5
rLE range low 24.8
\(\boldsymbol{r}\) SE restore 6.8
rEd 1 RTD 14.7

\section*{S}

SEI seconds 7.2, 7.3
SHY5 slidewire hysteresis 4.11
[5II己 silencing 24.18
SIII 3 silencing 34.21
5II 4 silencing 44.24
SoRH soak 7.3
SDFE software revision 6.3
[5n-- serial number 6.3
SP set point 7.2
[EEPP step 7.1
SEPE set point step 7.2
[SE SP step type 7.2
T
Equt test outputs 6.6
W
LIE waitfor event input 7.3
LUIPr waitfor process crossover value 7.3

\section*{Specifications}

\section*{Specifications (1306)}

\section*{Control Mode}
- Single input, quad output, optional retransmit of set point or process variable.
- Programmable direct- and reverse-acting control outputs.
- 4-file, 6 steps per file, time/temperature profile or fixed-set-point control.
- Ramp-rate or time-based programming.
- Selectable control status following power loss.

\section*{Agency Approvals}
- CE: 89/336/EEC Electromagnetic Compatibility Directive.

EN 50081-2: 1994 Emissions.
EN 50082-2: 1994 Immunity.
- 73/23/EEC Low Voltage Directive.

EN 61010-1: 1993 Safety.
- UL \#873, C-UL File \#E43684
- NEMA 4X

Operator Interface
- Dual, four digit LED displays.

Upper: 0.4 inch ( 10 mm ).
Lower: 0.3 inch ( 8 mm ).
- Mode, Hold/Run, Display, Up and Down keys.

\section*{Accuracy}
- Calibration accuracy and sensor conformity: \(\pm 0.1 \%\) of span, \(\pm 1 \mathrm{LSD}, 77^{\circ} \mathrm{F} \pm 5^{\circ} \mathrm{F}\left(25^{\circ} \mathrm{C} \pm 3^{\circ} \mathrm{C}\right)\) ambient and rated line voltage \(\pm 10 \%\).
- Accuracy span: \(1000^{\circ} \mathrm{F}\left(540^{\circ} \mathrm{C}\right)\) minimum.
- Temperature stability: \(\pm 0.2^{\circ} \mathrm{F} /{ }^{\circ} \mathrm{F}\left(0.1^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{C}\right)\) change in ambient.

\section*{Sensors/Inputs}
- Contact input for software function select (event input).
- Thermocouple Types B, C \({ }^{2}\), D \({ }^{2}\), E, J, K, N, R, S, T and Pt \(2^{2}\).
- RTD resolution in \(1^{\circ}\) or \(0.1^{\circ}\) RTD scales.
- Process variables: \(0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}, 0-5 \mathrm{~V}=(\mathrm{dc}), 1-5 \mathrm{~V}=(\mathrm{dc})\), and \(0-10 \mathrm{~V}=(\mathrm{dc})\).
- Slidewire or digital event input options.
- Sensor break protection de-energizes system for safety. Latching or non-latching.

\section*{Input Range}

Specified temperature ranges represent the controller's operational span.

\section*{- Thermocouple}

Available with basic or universal signal conditioner
\begin{tabular}{lrr} 
Type \(\mathrm{C}^{2}\) & 32 to \(4200^{\circ} \mathrm{F}\) & \(\left(0\right.\) to \(\left.2316^{\circ} \mathrm{C}\right)\) \\
Type \(\mathrm{D}^{2}\) & 32 to \(4200^{\circ} \mathrm{F}\) & \(\left(0\right.\) to \(\left.2316^{\circ} \mathrm{C}\right)\) \\
Type E & -328 to \(1470^{\circ} \mathrm{F}\) & \(\left(-200\right.\) to \(\left.799^{\circ} \mathrm{C}\right)\) \\
Type J & 32 to \(1500^{\circ} \mathrm{F}\) & \(\left(0\right.\) to \(\left.816^{\circ} \mathrm{C}\right)\) \\
Type K & -328 to \(2500^{\circ} \mathrm{F}\) & \(\left(-200\right.\) to \(\left.1371^{\circ} \mathrm{C}\right)\) \\
Type N & 32 to \(2372^{\circ} \mathrm{F}\) & \(\left(0\right.\) to \(\left.1300^{\circ} \mathrm{C}\right)\) \\
Type T & -328 to \(750^{\circ} \mathrm{F}\) & \(\left(-200\right.\) to \(\left.399^{\circ} \mathrm{C}\right)\) \\
\({\text { Pt } 2^{2}}^{32}\) & 32 to \(2543^{\circ} \mathrm{F}\) & \(\left(0\right.\) to \(\left.1395^{\circ} \mathrm{C}\right)\)
\end{tabular}

Available with universal signal conditioner
\begin{tabular}{lrr} 
Type B & 1598 to \(3300^{\circ} \mathrm{F}\) & \(\left(870\right.\) to \(\left.1816^{\circ} \mathrm{C}\right)\) \\
Type R & 32 to \(3200^{\circ} \mathrm{F}\) & \(\left(0\right.\) to \(\left.1760^{\circ} \mathrm{C}\right)\) \\
Type S & 32 to \(3200^{\circ} \mathrm{F}\) & \(\left(0\right.\) to \(\left.1760^{\circ} \mathrm{C}\right)\)
\end{tabular}

Type S 32 to \(3200^{\circ} \mathrm{F}\)
(0 to \(1760^{\circ} \mathrm{C}\) )
- RTD Resolution (DIN or JIS)
\(1^{\circ}(\) DIN \() \quad-328\) to \(1472^{\circ} \mathrm{F} \quad\left(-200\right.\) to \(\left.800^{\circ} \mathrm{C}\right)\)
\(1^{\circ}\) (JIS) -328 to \(1166^{\circ} \mathrm{F} \quad\left(-200\right.\) to \(\left.630^{\circ} \mathrm{C}\right)\)
\(0.1^{\circ}\) (DIN and JIS)
-99.9 to \(999.9^{\circ} \mathrm{F} \quad\left(-73.3\right.\) to \(537.7^{\circ} \mathrm{C}\) )
- Process
-999 to 9999 units for all: 0-5V \(=(\mathrm{dc}) ; 1-5 \mathrm{~V}=(\mathrm{dc}) ; 0-10 \mathrm{~V}=(\mathrm{dc})\);
\(0-20 \mathrm{~mA}\); and 4-20mA.
- Input 2 slidewire feedback 100 to \(1200 \Omega\).

\section*{Output Options}
- Solid-state relay, Form A, 0.5A @ 24V~ (ac) min., 253V~ (ac) max., opto-isolated, burst fire switching. With or without contact suppression. Off-state output impedance is \(20 \mathrm{k} \Omega\) with RC suppression, \(31 \mathrm{M} \Omega\) without contact suppression.
- Open collector or switched dc signal provides a minimum turn-on voltage of \(3 \mathrm{~V}=\) (dc) into a minimum \(500 \Omega\) load; maximum on voltage not greater than \(32 \mathrm{~V}=\) (dc) into an infinite load, isolated.
- Electromechanical relay \({ }^{1}\), Form C, 5A @ 120/240V~ (ac), 6A @ \(28 \mathrm{~V}=\) ( dc ), \(1 / 8 \mathrm{hp}\). @ 120V~ (ac), 125VA @ 120V~ (ac). With or without contact suppression. Off-state output impedance with RC suppression is \(20 \mathrm{k} \Omega\).
- Process, \(0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}\) into \(800 \Omega\) maximum, \(0-5 \mathrm{~V}=(\mathrm{dc})\), \(1-5 \mathrm{~V}=\) (dc) or \(0-10 \mathrm{~V}=\) (dc) into \(1 \mathrm{k} \Omega\) minimum reverse acting, isolated.
- Electromechanical relay \({ }^{1}\), Form A/B, 5 A @ 120/240V~ (ac), 6A @ 28V= (dc), 1/8 hp. @ 120V~ (ac), 125VA @ 120V~ (ac). Without contact suppression.
- External transmitter power supply, 5, 12 or \(20 \mathrm{~V}=\) (dc) @ 30 mA .
- EIA/TIA-232 communications or EIA/TIA-485, EIA/TIA-422 communications, opto-isolated.
- Retransmit: 0-20mA, 4-20mA with \(600 \Omega\) max. load impedance, or \(0-5 \mathrm{~V}=\) (dc), \(1-5 \mathrm{~V}=\) (dc) and \(0-10 \mathrm{~V}=\) (dc) with \(500 \Omega\) min. load impedance.

\section*{Line Voltage/Power}
- \(100-240 \mathrm{~V} \approx(\mathrm{ac} / \mathrm{dc})+10 \%,-15 \% ; 50 / 60 \mathrm{~Hz}, \pm 5 \%\).
- 24 to \(28 \mathrm{~V} \approx(\mathrm{ac} / \mathrm{dc})+10 \%,-15 \% ; 50 / 60 \mathrm{~Hz}, \pm 5 \%\).
- Fused internally (factory replaceable only) Slo-Blo type (time-lag): \(2 \mathrm{~A}, 250 \mathrm{~V}\) for high voltage versions;
\(5 \mathrm{~A}, 250 \mathrm{~V}\) for low voltage versions.
- Power consumption 16VA maximum.
- Non-volatile memory retains data if power fails.

\section*{Operating Environment}
- 32 to \(130^{\circ} \mathrm{F}\left(0\right.\) to \(\left.55^{\circ} \mathrm{C}\right)\).
- 0 to \(90 \%\) RH, non-condensing.

Storage Temperature
- -40 to \(185^{\circ} \mathrm{F}\left(-40\right.\) to \(\left.85^{\circ} \mathrm{C}\right)\).

\section*{Terminals}
- \#6 compression universal head screws, accepts 28-14 gauge wire.

\section*{Controller Weight}
- \(1.0 \mathrm{lb}(0.45 \mathrm{~kg})\).

Shipping Weight
- 3.01 lbs ( 1.35 kg ).

Sample/Update Rates
- 1 input: 10 Hz .
- 2 inputs: 5 Hz .
- Retransmit: 1 Hz .
- Remote set point: 1 Hz .
- PID: 10 Hz .
- Control outputs: 10 Hz .
- Alarm outputs: 1 Hz .
- Display: 2 Hz .

Resolution
- Inputs: 16 bits.

Series 981/982
Power Supply \& Mounting
\(=100\) to \(240 \mathrm{~V}=(\mathrm{ac} / \mathrm{dc})\) nominal, horizontal mounting
\(=100\) to \(240 \mathrm{~V} \approx\) (ac/dc) nominal, vertical mounting
\(=24\) to \(28 \mathrm{~V} \approx(\mathrm{ac} / \mathrm{dc})\) nominal, horizontal mounting
\(=24\) to \(28 \mathrm{~V} \approx\) ( \(\mathrm{ac} / \mathrm{dc}\) ) nominal, vertical mounting
Software
\(C=\) Standard (4-file, 6 step per file, program capability)
Input 1
\(=\) Basic thermocouple signal conditioner (excluding Type B, R, and S)
\(=\) Universal signal conditioner (see input range information)
Input 2
\(=\) None
\(=\) Slidewire feedback (see range information)
\(=\) Second digital event (one digital event is standard on all units)
utput 1
\(=\) Solid-state relay, Form A, 0.5 A , with RC suppression
\(=\) Switched dc or open collector, isolated
\(=\) Electromechanical relay \({ }^{1}\), Form C, 5 A with RC suppression
\(=\) Electromechanical relay \({ }^{1}\), Form C, 5A without contact suppression
\(=\) Universal process, \(0-5 \mathrm{~V}=(\mathrm{dc}), 1-5 \mathrm{~V}=(\mathrm{dc}), 0-10 \mathrm{~V}=(\mathrm{dc})\), \(0-20 \mathrm{~mA}=(\mathrm{dc}), 4-20 \mathrm{~mA}=(\mathrm{dc})\), isolated
\(=\) Solid-state relay, Form A, 0.5 A , without contact suppression
Output 2
A = None
\(=\) Solid-state relay, Form A, 0.5 A , with RC suppression
= Switched dc or open collector, isolated
\(=\) Electromechanical relay \({ }^{1}\), Form C, 5 A with RC suppression
\(=\) Electromechanical relay \({ }^{1}\), Form C, 5A without contact suppression
\(=\) Universal process \(0-5 \mathrm{~V}=(\mathrm{dc}), 1-5 \mathrm{~V}=(\mathrm{dc}), 0-10 \mathrm{~V}=(\mathrm{dc})\), \(0-20 \mathrm{~mA}=(\mathrm{dc}), 4-20 \mathrm{~mA}=(\mathrm{dc})\), isolated
\(=\) Solid-state relay, Form A, 0.5 A , without contact suppression
\(\mathrm{T}=\) External signal conditioner power supply, 5, 12 or \(20 \mathrm{~V}=\) (dc) @ 30 mA
Output 3
\(A=\) None
\(B=\) Solid-state relay, Form A, 0.5 A , with RC suppression
\(C=\) Switched dc, isolated
\(J=\) Electromechanical relay \({ }^{1}\), Form A or B, 5 A without contact suppression
\(=\) Solid-state relay, Form A, 0.5 A without contact suppression
\(=\) Retransmit, \(0-20 \mathrm{~mA}=(\mathrm{dc}), 4-20 \mathrm{~mA}=(\mathrm{dc})\)
\(=\) Retransmit, \(0-5 \mathrm{~V}=\) (dc), \(1-5 \mathrm{~V}=\) (dc), \(0-10 \mathrm{~V}=\) (dc)
\(=\) External signal conditioner power supply, 5, 12 or 20V \(=\) (dc) @ 30mA
utput 4
\(=\) None
\(=\) Solid-state relay, Form A, 0.5 A , with RC suppression
\(=\) Switched dc or open collector, isolated
\(=\) Electromechanical relay \({ }^{1}\), Form C, \(5 A\) with RC suppression
\(=\) Electromechanical relay \({ }^{1}\), Form C, 5A without contact suppression
\(=\) Solid-state relay, Form A, 0.5 A without contact suppression
\(=\) EIA/TIA-232 communications, opto-isolated
\(=\) EIA/TIA-485, EIA/TIA-422 communications, opto-isolated
\(=\) External signal conditioner power supply, 5,12 or \(20 \mathrm{~V}=(\mathrm{dc}) @ 30 \mathrm{~mA}\)
\(=\) EIA/TIA-232 or EIA/TIA 485, opto-isolated
Display Color (Upper/Lower)
GG = Green/Green
\(R G=\) Red/Green
GR = Green/Red
RR \(=\) Red/Red

1 Electromechanical relays warranted for 100,000 closures only. Solid-state switching devices recommended for applications requiring fast cycle times or extended service life.
2 Not an ANSI symbol.
UL \(^{\circledR}\) is a registered trademark of the Underwriters Laboratories, Inc.
Slo- \(\mathrm{Blo}^{\circledR}\) is a registered trademark of Littelfuse, Inc.

\section*{NOTE: User documentation may be available in French, German, Spanish, Italian and Dutch, as well as English. Check Watlow's website (www.watlow.com/) for availability. Specify language at time of order.}


Déclare que le produit suivant : Français
Désignation: \(\quad\) Série 981, 982, 983, 984
Numéro(s) de modèle(s) : 98 (12 3 ou 4) (lettre quelconque) - (1 ou 2) - (0 3 ou 5) (BCDEF ou K) (ABCDEFK ou T) - (ABC JKMN ou T) (ABCDEKRS ou T) (deux lettres quelconques)
Classification: Commande, installation catégorie II, degré de pollution II
Tension nominale : \(\quad 100\) à \(240 \mathrm{~V} \sim 0 u 24\) à 28 V
Fréquence nominale \(50 / 60\) Hz
Consommation
d'alimentation nominale :
16 VA maximum
Conforme aux exigences de la (ou des) directive(s) suivantes de l'Union Européenne figurant aux sections correspondantes des normes et documents associés ci-dessous :

89/336/EEC Directive de compatibilité électromagnétique
EN 50082-2 : 1995 Norme générique d'insensibilité électromagnétique, Partie 2 : Environnement industriel
EN 61000-4-2 : 1995 Décharge électrostatique
EN 61000-4-4 : 1995 Courants électriques transitoires rapides
EN 61000-4-3: 1996 Insensibilité à l'énergie rayonnée
EN 61000-4-6: 1996 Insensibilité à l'énergie par conduction
ENV 50204: 1995 Téléphone cellulaire
EN 50081-2: 1994 Norme générique sur les émissions électromagnétiques, Partie 2 : Environnement industriel
EN 55011: 1991 Limites et méthodes de mesure des caractéristiques d'interférences du matériel radiofréquence industriel, scientifique et médical (Groupe 1, Classe A)
EN 61000-3-2 : 1995 Limites d'émission d'harmoniques
EN 61000-3-3 : 1995 Limitations d'écarts de tension et de papillotement
73/23/EEC Directive liée aux basses tensions
EN 61010-1 : 1993 Exigences de sécurité pour le matériel électrique de mesure, commande et de laboratoire, Partie 1 : Exigences générales

Erklärt, daß das folgende Produkt:
Deutsch
Beschreibung: Serie 981, 982, 983, 984
Modellnummer(n): 98 (123 oder 4) (beliebiger Buchstabe) - (1 oder 2) (0 3 oder 5) (B C D E F oder K) (A B C D E F K oder T) - (A B C J K M N oder T) (A B C D E K R S oder T) (2 beliebige Buchstaben)
Klassifikation: Regelsystem, Installationskategorie II

Nennfrequenz:
100 bis 240 V~ oder 24 bis 28 V

Stromverbrauch: \(50 / 60 \mathrm{~Hz}\)

Erfüllt die wichtigsten Normen der folgenden Anweisung(en) der Europäischen Union unter Verwendung der untenstehenden einschlägigen Dokumente:

89/336/EEC Elektromagnetische Übereinstimmungsanweisung
EN 50082-2: 1995 EMC-Rahmennorm für Störsicherheit, Teil 2: Industrielle Umwelt
EN 61000-4-2: 1995 Elektrostatische Entladung
EN 61000-4-4: 1995 Elektrische schnelle Stöße
EN 61000-4-3: 1996 Strahlungsimmunität
EN 61000-4-6: 1996 Leitungsimmunität
ENV 50204: 1995 Mobiltelefon
EN 50081-2: 1994 EMC-Rahmennorm für Emissionen, Teil 2: Industrielle Umwelt
EN 55011: 1991 Beschränkungen und Methoden der Messung von Funkstörungsmerkmalen industrieller, wissenschaftlicher und medizinischer Hochfrequenzgeräte (Gruppe 1, Klasse A)
EN 61000-3-2: 1995 Grenzen der Oberwellenstromemissionen
EN 61000-3-3: 1995 Grenzen der Spannungsschwankungen und Flimmern
72/23/EEC Niederspannungsrichtlinie zu entsprechen
EN 61010-1: 1993 Sicherheitsrichtlinien für Elektrogeräte zur Messung, zur Steuerung und im Labor, Teil 1: Allgemeine Richtlinien

Declara que el producto siguiente: Español
Designación
Series 981, 982, 983, 984
Números de modelo: 98 (1 23 ó 4)(Cualquier letra) - (1 ó 2)(0 3 ó 5)(B C DEFoK)(ABCDEFKoT) (ABCJKMNoT)(A BCDEKRSoT)(Cualquier combinación de dos letras
Clasificación: Control, categoría de instalación II, grado de contaminación ambiental II
Tensión nominal: \(\quad 100\) a \(240 \mathrm{~V} \sim 024\) a 28 V
Frecuencia nominal: \(\quad 50 / 60 \mathrm{~Hz}\)
Consumo nominal de energía: 16 VA máximo
Cumple con los requisitos esenciales de las siguientes directivas de la Unión Europea, usando las secciones pertinentes de las reglas normalizadas y los documentos relacionados que se muestran:

89/336/EEC - Directiva de compatibilidad electromagnética EN 50082-2: 1995 Norma de inmunidad genérica del EMC, parte 2: Ambiente industrial
EN 61000-4-2: 1995 Descarga electrostática
EN 61000-4-4: 1995 Perturbaciones transitorias eléctricas rápidas
EN 61000-4-3: 1996 Inmunidad radiada
EN 61000-4-6: 1996 Inmunidad conducida
ENV 50204: 1995 Teléfono portátil
EN 50081-2: 1994 Norma de emisión genérica del EMC, parte 2: Ambiente industrial
EN 55011: 1991 Límites y métodos de medición de características de perturbaciones de radio correspondientes a equipos de radiofrecuencia industriales, científicos y médicos (Grupo 1, Clase A)
EN 61000-3-2: 1995 Límites para emisiones de corriente armónica
EN 61000-3-3: 1995 Limitaciones de fluctuaciones del voltaje
73/23/EEC Directiva de baja tensión
EN 61010-1: 1993 Requerimientos de seguridad para equipos eléctricos de medición, control y uso en laboratorios, Parte 1: Requerimientos generales
\begin{tabular}{ll} 
Erwin D. Lowell & Winona, Minnesota, USA \\
Name of Authorized Representative & Place of Issue \\
General Manager & \begin{tabular}{l} 
January 24, 1996 \\
Title of Authorized Representative \\
Date of Issue
\end{tabular} \\
\hline Signature of Authorized Representative &
\end{tabular}

Watlow Series 982 User's Manual
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